

**LEVEL MONITOR  
MODEL 120A**





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# 1. INTRODUCTION

The Model 120 Level Monitor is a microprocessor based instrument which accepts a 4-20mA input and displays level and contents. It is powered entirely from the 4-20mA loop and, therefore, does not require an external power source.

Level is displayed in a bar graph as 0...100%. The contents are a 7 digit numeric display which can be spanned in any engineering units.

The instrument is fully programmable; the user can program alarm settings, span & zero levels and non-linear correction points. Calculation constants are also set from the front panel and are stored in a non-volatile memory which retains data indefinitely.

The Model 120 Level Monitor conforms to the EMC-Directive of the Council of European Communities 2004/108/EC, the LVD directive 2006/95/EC and the following standards:

*EN61326:2013*

Electrical equipment for measurement, control and laboratory use – EMC requirements : Residential, Commercial & Light Industry Environment & Industrial Environment.

*EN61010:2010*

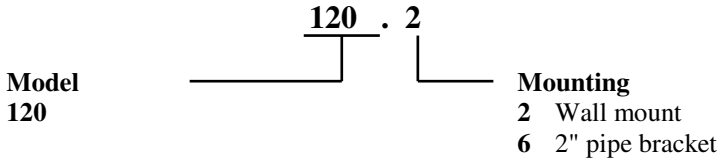
Safety requirements for electrical equipment for measurement, control, and laboratory use.

In order to comply with these standards, the wiring instructions in Section 7.5 must be adhered to.

## 2 Introduction

### 1.1 MODEL NUMBER DESIGNATION

The Model Number of the 120 describes the input and output options installed and the mounting options.



**Tank Conversion Software**  
220CSW

## 2. SPECIFICATION

### *General*

Display:	Continuously powered LCD.
Level:	30mm bar graph.
Level Span:	0...100% per full scale.
Contents:	7 digit with 4½ digit resolution, 12mm (0.5") high.
Contents Span:	The units of measure (eg. litres) at full scale of input signal. The contents span is programmable in the range of 0.000...9,999,999.
Volume:	Either "Volume" or "Contents" can be displayed. This is user programmable.
Decimal Points:	Decimal point positions for contents is programmable in range of 0...3 decimal points.
Signal Type:	4-20mA.

### *4-20mA*

Resolution and Linearity:	0.05% of span.
Accuracy:	0.05% of span @ 25°C.
	0.1% (typically) of span full temperature range.
Update Time:	0.5 second.
Connection:	2 wire.
Voltage Drop:	2.5V maximum.

### *Outputs*

Type:	4 open collector output alarms suitable for driving dc solenoids or external relays. The outputs provide: <ol style="list-style-type: none"> <li>1. high-high.</li> <li>2. high.</li> <li>3. low.</li> <li>4. low-low.</li> </ol>
Switching Power:	200mA. 30Vdc maximum.
Saturation Voltage:	0.8Vdc across the output in the "on" state.
Isolation:	All outputs are separately opto-isolated.

## 4 Specification

### *Physical*

Operating Temperature:	-20°C to 60°C.
Dimensions:	97mm (3.8") high x 150mm (5.9") wide x 41mm (1.6") deep (not including cable glands).
Protection:	Nema 4X or IP67 standards.
Cable Entry:	Cable glands.
Mounting:	Universal mounting bracket is supplied as standard.
Pipe Mounting:	A galvanised metal bracket is available which enables the instrument to be mounted on a 2" horizontal or vertical pipe.



# 3. OPERATION

The Model 120 Level Monitor accepts a 4-20mA input signal from a level sensor such as a pressure transmitter, ultrasonic sensor or capacitance probe. The instrument is powered entirely from the loop and, therefore, requires no external power or internal batteries.

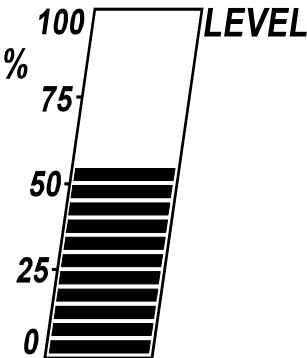
The instrument is fully programmable with all operating parameters and calculation constants programmable from the front panel (see Section 4.1). The setup parameters are stored in a non-volatile memory and are retained for at least 10 years in the event of a power loss.

## 3.1 DISPLAY

The display of the Model 120 comprises of:

*Level Bar Graph*  
*Contents*

### 3.1.1 Level Bar Graph



The level bar graph displays the vertical level of liquid as a percentage.

Inputs of 4mA and 20mA can be programmed to correspond to 0% and 100% respectively, or can be inverted so that 4mA will correspond to 100% and 20mA will correspond to 0%.

Note that the level is corrected for density (if applicable) as described in Section 3.7.

## 6 Operation

### 3.1.2 Contents

The contents is a 7 digit numeric display where the span can be programmed during setup to read in any engineering units. The contents are displayed with 4½ resolution in respect to the maximum contents.

For example, if the maximum contents is 1234567, the display will show up to 5 digits plus trailing zeros. At different inputs the following will be displayed:

1234567 will be displayed as 1234500; 234567 will be displayed as 2345000.

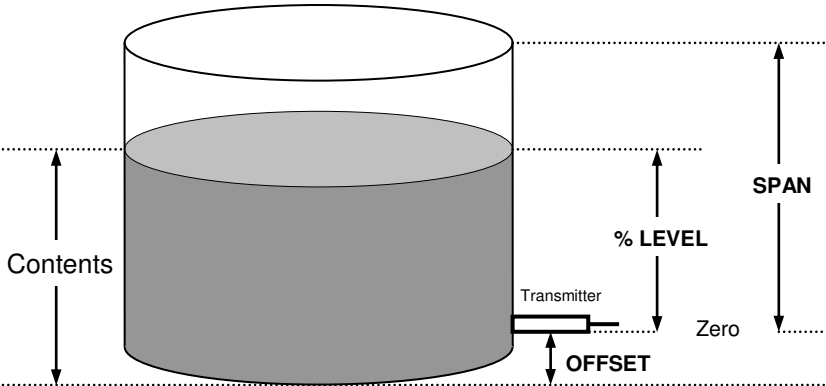
However, if the first digit is greater than 1, then up to 4 digits only will be displayed with trailing zeros. For example, if the maximum contents is 2345678, then at different inputs:

2345678 will be displayed as 2345000; 345678 will be displayed as 345000.

### ***CALCULATION OF CONTENTS***

For a **linear tank** the contents is calculated as follows:

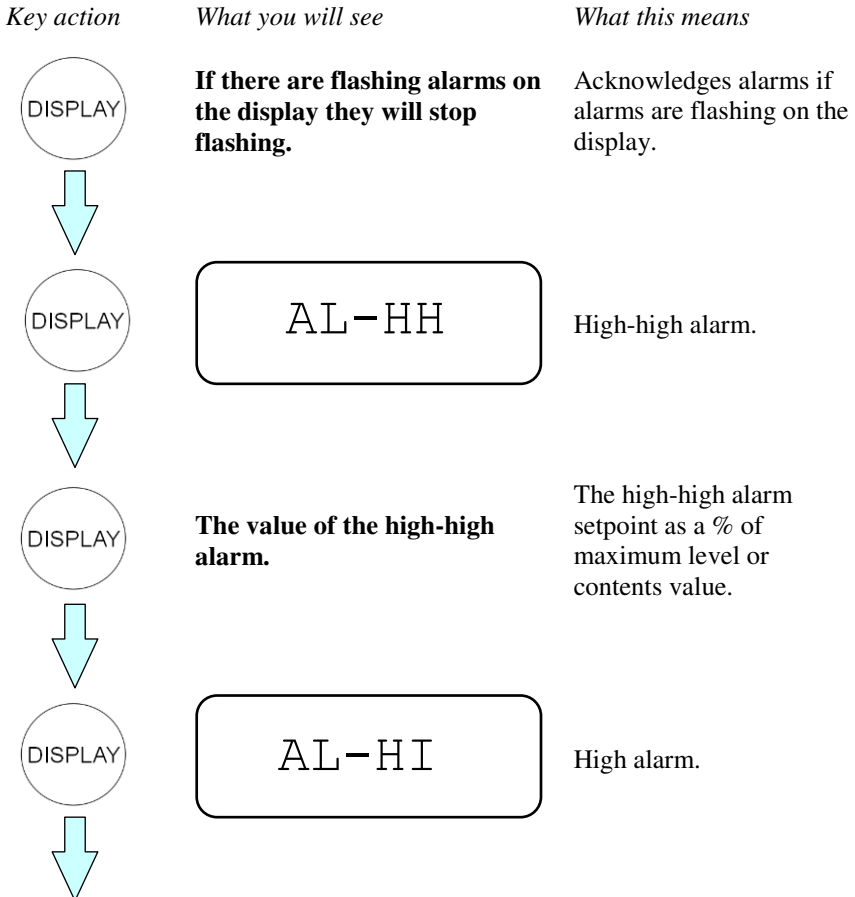
$$\text{Contents} = (\text{Span}) \times (\% \text{ Level}) + \text{Offset}$$



## 3.2 FRONT PANEL OPERATION

### 3.2.1 Displaying Data

The alarm setpoints and density correction factor can be viewed by pressing the DISPLAY key.



## 8 Operation

*Key action*

*What you will see*

*What this means*

DISPLAY

**The value of the high alarm.**

The high alarm setpoint as a % of maximum level or contents value.



DISPLAY

AL-LO

Low alarm.



DISPLAY

**The value of the low alarm.**

The low alarm setpoint as a % of maximum level or contents value.



DISPLAY

AL-LL

Low-low alarm.



DISPLAY

**The value of the low-low alarm.**

The low alarm setpoint as a % of maximum level or contents value.



*Key action*

*What you will see*

*What this means*



Density correction factor.



**The value of the density correction factor.**

A factor for those applications where the density of the fluid in the tank is likely to change (default of 1.000).



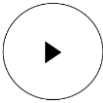
**Returns to contents display.**

## 10 Operation

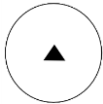
### 3.2.2 Changing Data

Each of the above parameters can be changed as follows:

1. Pressing the DISPLAY key consecutively until the numeric value of the parameter to be changed appears (as described in the previous diagram).
2. This value can then be changed using the following keys:



This key steps from digit to digit, causing the digit to flash. Only flashing digits can be changed.



This key increments the flashing digit.

#### Example.

To change the high alarm setpoint to 75:

1. Press DISPLAY until the value of the high alarm appears. This will be the value after AL-HI.
2. The first digit is flashing, this means it can be changed. Using the  $\triangle$  key, this digit is changed to 7.
3. The  $\triangleright$  key is pressed so that the second digit flashes.
4. Using the  $\triangle$  key, this digit is changed to 5.

Note that the Model 120 can be programmed so that the above parameters cannot be changed, see Section 4.1.

### 3.2.3 Timeout Condition

Upon entering the display mode, if no key is pressed for 10 seconds, the display returns to the contents display with alarm acknowledgment cleared.

## 3.3 TEST MODE

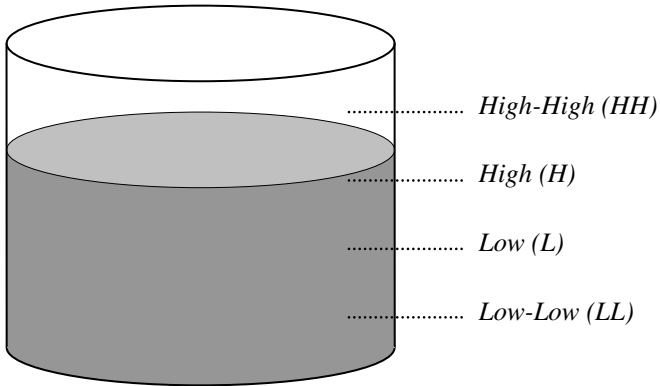
The 120 has a test mode which can be entered by simultaneously pressing all 3 front panel keys. There are 3 tests:

<i>Low Test</i>	By pressing the $\triangleright$ key, the low and low-low alarms outputs will be energised.
<i>High Test</i>	By pressing the $\triangle$ key, the high and high-high alarm outputs will be energised.
<i>Display Test</i>	By pressing the DISPLAY key, all segments of the display will flash.

To exit the test mode all three keys are pressed simultaneously.

### 3.4 ALARMS

The Model 120 has 4 alarm outputs:



The alarms can be assigned to **level** or **contents** which is done during programming (see Section 4.1). Each alarm is individually programmed as a percentage (0-100%) of level or contents.

All of the alarms have open collector outputs and are separately isolated via optoisolators. The outputs are internally protected against voltage spikes caused by relays and coils.



### 3.4.1 Types of Alarms

#### 3.4.1.1 Alarm Output

The Model 120 can be programmed for the alarm outputs to operate in one of two ways:

1. the alarm outputs can **energise** (switch on) during an alarm condition, or
2. the alarm outputs can **de-energise** (switch off) during an alarm condition.

#### 3.4.1.2 High Alarms

The high alarms will be activated when the contents or level in the tank increase above the high alarm setpoints. These alarms will be deactivated when the contents or level falls below these programmed setpoints.

When setting the alarms, the high-high alarm should be set higher than the high alarm.

#### 3.4.1.3 Low Alarms

The low alarms will be activated when the level or contents in the tank falls below the low alarm setpoints. These alarms will be deactivated when the level exceeds the programmed setpoint.

Similarly, when setting the low alarms, the low-low alarm should be set below the low alarm.

## 14 Operation

### 3.4.2 Alarm Deadband

To prevent an alarm toggling on and off when the level is close to the setpoint, a user programmable deadband is provided. The deadband is a percentage (0-100%) of the maximum level or contents.

#### Example 1.

If the low alarm is set to 20% and the deadband is set to 5%, the alarm will be activated when the level reaches 20%. The alarm will then stay activated until the level increases above 25%.

#### Example 2.

If the high alarm and deadband are set at 80% and 5% respectively, the alarm will be activated at 80% and will stay activated until the level falls below 75%.

### 3.4.3 Alarm Action

When an alarm condition exists the Model 120 will act in the following way:

1. The appropriate alarm output will be activated.
2. The display will flash the name of the alarm.
3. In some cases these alarms may be acknowledged from the front panel. This will depend on whether they are programmed as **continuous** or **acknowledgeable alarms**. This is set up during programming (see Section 4.1).

The differences between acknowledging continuous and acknowledgeable alarms are described in table on the following page.

Acknowledgeable Alarms	Continuous Alarms
1. These alarms are acknowledged by pressing the DISPLAY key.	1. A continuous alarm cannot be acknowledged.
2. Once the alarm is acknowledged the flashing on the LCD will cease, with the alarm message remaining solid. The message will remain on the screen until the alarm condition no longer exists.	2. The flashing on the LCD cannot be stopped and will keep flashing until the alarm condition no longer exists.
3. Once the alarm is acknowledged, the alarm output will be deactivated.	3. The alarms will only be deactivated when the level (or contents) is outside alarm conditions.
<p>Note that acknowledging the LL alarm will also acknowledge (and deactivate) the L alarm. Similarly, acknowledging the HH alarm will also acknowledge (and deactivate) the H alarm.</p>	

## 16 Operation

### 3.4.4 Setting Alarms

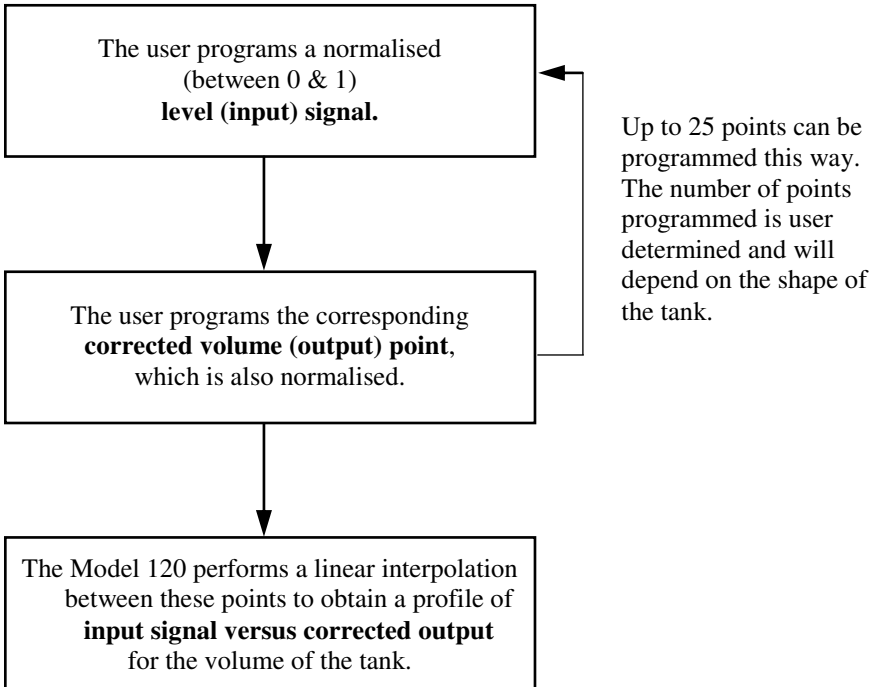
To set any of the alarms:

1. Press the DISPLAY key until the name of the alarm to be changed appears (see Section 3.2.1).
2. Use the  $\blacktriangleright$  and  $\triangleleft$  keys to change the value of the alarm.
3. Press the DISPLAY key until the original level/contents screen appears.

### 3.5 NON-LINEARITY

The Model 120 can be programmed to correct for the non-linearities in irregular shaped tanks. These tanks have a non-linear relationship between the height of liquid and the volume of liquid.

A correction table, which corrects for non-linearities between the level signal and the volume, can be programmed during setup. This table works as follows:



## 18 Operation

### ***DETERMINING THE NON-LINEAR CORRECTION TABLE***

Data on tank non-linearity is usually supplied by the tank manufacturer, in the form of strapping tables. If this data is not available, the user will need to determine the relationship between level and volume. This can be done mathematically by equations, or experimentally, by conducting physical measurements.

In either case, the data must be normalised. An example of this is shown below:

#### **Example.**

A spherical tank has a diameter of 10m. The zero is at 0.5m and the span is 10m. The following 15 point relationship has been determined:

	Input		Volume	Normalised Inputs for Table	
	Level (m)	Level T'mitter Output	m <sup>3</sup>	Input	Output
	0.5	4mA	3.796	0.000	0.000
<b>1</b>	1.094		17.421	0.0630	0.026
<b>2</b>	1.688		39.699	0.125	0.069
<b>3</b>	2.281		69.314	0.188	0.126
<b>4</b>	2.875		104.951	0.250	0.195
<b>5</b>	3.469		145.295	0.313	0.272
<b>6</b>	4.063		189.031	0.375	0.356
<b>7</b>	4.656		234.844	0.438	0.444
<b>8</b>	5.250		281.418	0.500	0.534
<b>9</b>	5.844		327.438	0.563	0.623
<b>10</b>	6.438		371.590	0.625	0.708
<b>11</b>	7.031		412.557	0.688	0.786
<b>12</b>	7.625		449.025	0.750	0.857
<b>13</b>	8.219		479.678	0.813	0.916
<b>14</b>	8.813		503.202	0.875	0.961
<b>15</b>	9.406		518.280	0.938	0.990
	10.000	20mA	523.599	1.000	1.000

Where,

$$\begin{aligned} \textit{Normalised Input} &= \frac{\text{Level}}{\text{Level at 20mA}} \\ &= \frac{\text{Level} - (\text{Level at Zero})}{(\text{Level at Span}) - (\text{Level at Zero})} \end{aligned}$$

If the Zero is  $> 0$

So, for example, at 9.406m the normalised input is:

$$\begin{aligned} &= \frac{(9.406 - 0.5)}{10 - 0.5} \\ &= 0.938 \end{aligned}$$

Similarly,

$$\begin{aligned} \textit{Normalised Output} &= \frac{\text{Volume}}{\text{Volume at 20mA}} \\ &= \frac{\text{Volume} - (\text{Volume at Zero})}{(\text{Volume at Span}) - (\text{Volume at Zero})} \end{aligned}$$

If the Zero is  $> 0$

So, for example, at 9.406m the volume is 518.280m<sup>3</sup> and the normalised output is:

$$\begin{aligned} &= \frac{(518.280 - 3.796)}{(523.599 - 3.796)} \\ &= 0.990 \end{aligned}$$

## 20 Operation

### ***SELECTING THE NUMBER OF POINTS FOR NON-LINEAR CORRECTION***

The user can program up to 25 points. However, the values at 4mA or 20mA which are set at 0 and 1 respectively, are not programmed. It is not always necessary to program all 25 points, as it will depend on the shape of the tank.

### **Tank Conversion Software**

Tank Conversion Software 220CSW can be used to calculate theoretical non-linearity correction tables for the most commonly used tank shapes (spherical, conical and cylindrical tanks).

The output from the program can be printed and is in a format suitable for direct programming into the Model 120. The program runs on a Windows 95 (or higher) operating system.

The software is only available from our website **[www.contrec.co.uk](http://www.contrec.co.uk)** and can be downloaded free of charge.



## 3.6 FILTERING

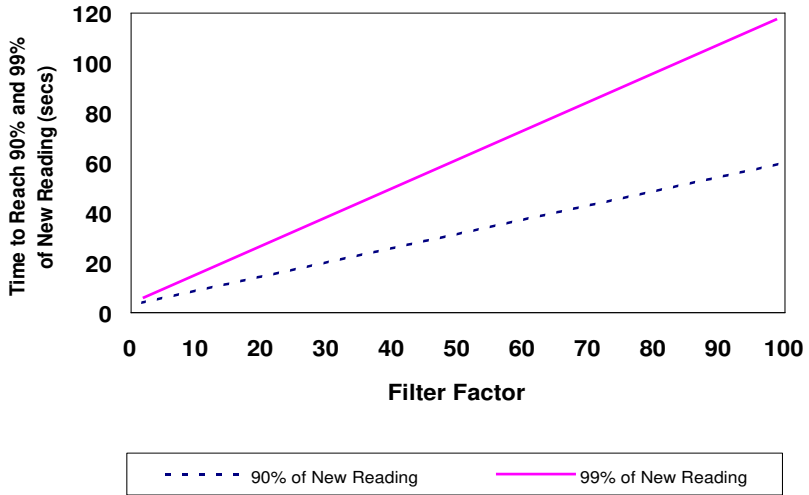
Input fluctuations caused by tank agitation can interfere with the stability of the level and contents readings. For this reason, the Model 120 has a digital filter which will average out these fluctuations and enable accurate readings.

The degree of filtering of the input signal can be adjusted, depending on the amount of fluctuation and the particular application. Values from 1 to 99 can be programmed, where 1 corresponds to no filtering and 99 corresponds to heavy filtering. Such flexibility in filtering means that highly accurate and stable readings can be obtained.

When programming the degree of filtering, it is advisable to start with no filtering (the factor equals 1) and gradually increase until a steady reading is obtained. It is important that the filtering is not too heavy because this will cause an overdamped response.

The following graph shows the time to reach 90% and 99% of a new reading for a step change in input signal.

**Filter Factor vs Time to Reach New Reading  
(for a step change in input signal)**



### 3.7 DENSITY CORRECTION

In some cases, a pressure transmitter will be used to provide the 4-20mA signal to the Model 120. In these cases, a density correction factor ( $K_D$ ) can be manually entered to compensate for those applications where the density of the fluid in the tank is likely to change. This would be the case if, initially, a particular fluid is stored in the tank and at a later stage a fluid of a different density is stored in the tank.

The density correction factor should initially be set to 1.000 when the Model 120 is calibrated for a given tank or vessel. If, at a later stage, a fluid of different density is stored in the tank, then it is only necessary to reprogram the density correction factor, rather than conducting a complete recalibration of the Model 120.

The density correction factor is the **ratio** of the density of the fluid which was originally in the tank, to the density of the new fluid.

This can be expressed as follows:

$$\text{Density Correction Factor } (K_D) = \frac{\text{Density Value at Calibration}}{\text{New Density Value}}$$

The density correction factor is then used to calculate level as:

$$\text{Level} = K_D \times \text{Input Signal}$$

where the input is normalised between 0% (4mA or 20mA if inverted) and 100% (20mA or 4mA).

The level is limited to 100% so that values of  $K_D$  which result in a level greater than this will be displayed as 100%.

## 24 Operation

### Example.

A tank is initially filled with toluene, which has a density at standard conditions of  $866 \text{ kg/m}^3$ . The Model 120 and a level transmitter are calibrated for the toluene in this tank and the density correction factor ( $K_D$ ) is set to 1.000.

At a later date, the tank is filled with acetone, whose density at standard conditions is  $791 \text{ kg/m}^3$ .

The density correction factor is calculated as follows:

$$K_D = \frac{866}{791} = 1.1$$

This value of  $K_D$  is then programmed during setup (see Section 3.2.2).

## 4. PROGRAMMING

The Model 120 is fully programmable with all parameters being stored in memory.

### To enter the Program Mode:

Remove the lower cover strip (the dark grey strip along the bottom of the front of the enclosure) and replace it the reverse side up. This brings a small magnet on the inside of the cover strip in contact with a reed switch inside the instrument. The word "Set" is then displayed.

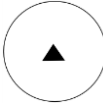
### To exit Program Mode:

The grey strip should be replaced the correct way up.

The key switch actions are as follows:



This key steps from digit to digit, causing the digit to flash.



This key will increment a flashing digit or change a parameter selection.



This key will step through the program sequence.

In stepping through the program sequence (using the DISPLAY key), the parameter description is displayed first, followed by the actual value or parameter. When a value or parameter can be changed it is shown as flashing.

## 4.1 PROGRAM STEPS

<i>Step</i>	<i>Display</i>	<i>Description</i>
1	<b>SET</b>	Select whether alarms are assigned to <b>level</b> or <b>contents</b> .
	<i>level</i>	Alarms are assigned to level.
	<i>Cont</i>	Alarms are assigned to contents.
2	<b>TYPE</b>	Select whether alarms are normally <b>energised</b> or normally <b>de-energised</b> .
	<i>NE</i>	Normally energised.
	<i>ND</i>	Normally de-energised.
3	<b>ACT</b>	Select type of alarm action, either <b>continuous</b> on alarm condition or <b> Cancels</b> when alarm is acknowledged.
	<i>N-AC</i>	Continuous on alarm condition.
	<i>AC</i>	Acknowledged and cancelled with display key.
4	<b>DBAND</b>	Alarm deadband.
	<b>xx.xx</b>	Program alarm deadband as a % of maximum level or contents value.
5	<b>FILT</b>	The <b>filter constant</b> for filtering the input signal.
	<i>1</i>	No filtering.
	<i>to</i>	
	<b>99</b>	Very heavy filtering.

<i>Step</i>	<i>Display</i>	<i>Description</i>
6	<b>INPUT</b>	Select input type; either <b>inverted</b> or <b>non-inverted</b> .
	<b>N-INV</b>	Non-inverted (zero at 4mA).
	<b>INV</b>	Inverted (zero at 20mA).
7	<b>DISP</b>	Select <b>enable</b> or <b>disable</b> . This will allow (enable) or not allow (disable) the user to change the alarm setpoints and the density correction factor from the DISPLAY key.
	<b>En</b>	Enable the changing of alarm setpoints and density correction factor.
	<b>Dis</b>	Disable changing alarm setpoints and density correction factor.
8	<b>UNIT</b>	Select whether the word " <b>Contents</b> " or " <b>Volume</b> " is displayed on the LCD.
	<b>Cont</b>	"Contents" will be displayed.
	<b>Vol</b>	The word "Volume" will be displayed in preference to Contents. (Note there is no difference in operation if Volume is selected.)
9	<b>C-DEC</b>	The position of the decimal point for the contents. The user can select 0, 1, 2, or 3 decimal places.
10	<b>C-SPAN</b>	Span of the contents. The span can be programmed in the range of 0.000 to 9,999,999.

## 28 Programming

<i>Step</i>	<i>Display</i>	<i>Description</i>
11	<b>C-00</b>	The zero of the contents. The zero can be programmed in the range of 0.000 to 9,999,999.
12	<b>LIN</b>	Select whether the input signal is <b>linear</b> or <b>non-linear</b> .
	<b>Lin</b>	Linear.
	<b>N-lin</b>	Non-linear.

*Steps 13-17 are displayed only if the input signal is non-linear.*

13	<b>No-PTS</b>	The number of points for non-linear correction. The user can program up to 25 points. Note the user does not program the values at 4mA or 20mA, which are set at 0 and 1 respectively.
14	<b>INP-01</b>	Non-linear correction Input Point #01. The input point for the first non-linear correction point is programmed in the range of 0.000 to 0.999. <b>Input points must be programmed in ascending order.</b>
15	<b>OUT-01</b>	The corresponding Output Point #01 for non-linear correction is programmed in the range of 0.000 to 0.999.
16	<b>INP-XXX</b>	Non-linear correction Input Point #XX. Subsequent input points are programmed in the range of 0.000 to 0.999.
17	<b>OUT-XXX</b>	The corresponding Output Point #XX. The corresponding output points are programmed.

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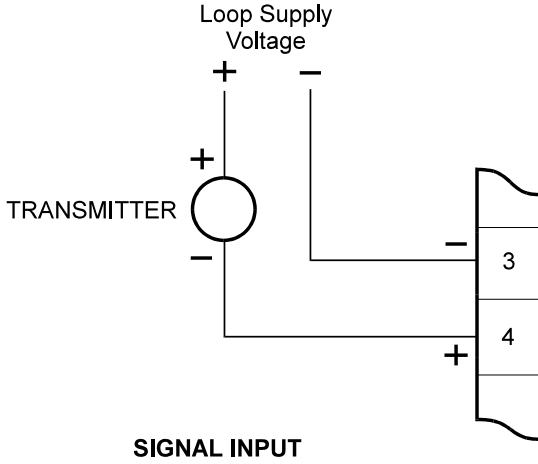
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18	<b>SOFT</b>	The software version used in the Model 120 is displayed.
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# 5. SIGNAL INPUT

The signal input is on terminals 3 and 4 and is connected as follows:



## 6. ALARM OUTPUTS

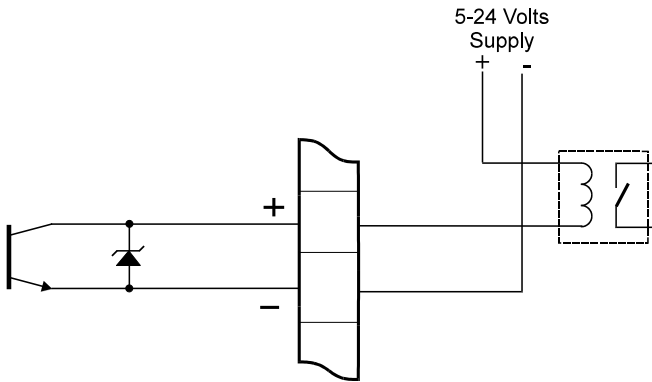
Open collector outputs are provided for high and low level alarms. The output can sink up to 200mA and can be used to power external relays, lights or audible alarms. The outputs are internally protected against voltage spikes.

Both outputs are separately isolated via opto-isolators.

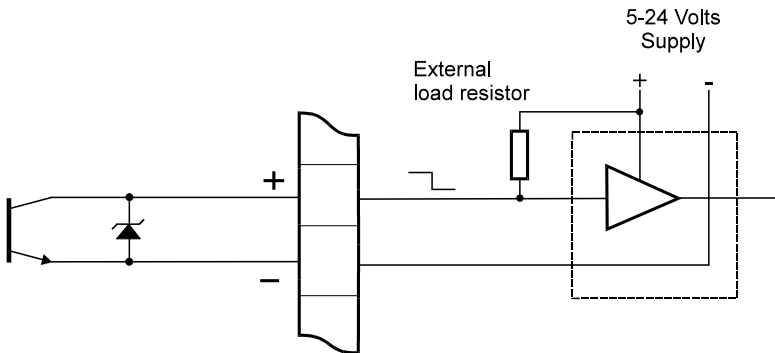
### *Alarm Output Specifications*

Maximum Current (sink):	200mA.
Maximum Voltage:	30Vdc.
Saturation Voltage:	0.8Vdc across outputs in energised state.
Isolation:	All outputs are separately isolated via opto-isolators.

Connections



ALARM RELAY



ALARM OUTPUT TO EXTERNAL CIRCUIT

# 7. INSTALLATION

## 7.1 WALL MOUNTING

A wall mounting bracket is supplied with each instrument. Round head screws should be used to attach the bracket to the wall (countersunk screws should not be used). The bracket is mounted first, with the “tray” section at the bottom. The instrument is then mounted on the bracket with two screws as shown below.



## 7.3 REMOVING THE FRONT PANEL

The front panel should be removed as follows:

1. Remove the top and bottom cover strips (ie. the dark plastic strip) by levering a screwdriver under one end.
2. Undo the screws retaining the front. Do not remove the screws, they are retained by O-rings.
3. Remove the front panel from the housing.

To replace the front cover, follow the above procedure in reverse. Ensure that the front panel is aligned at connector points before tightening the screws.

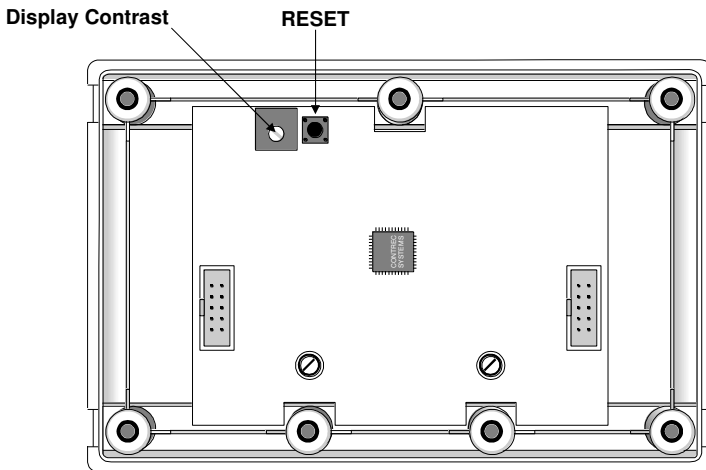
## 34 Installation



## 7.4 THE MAIN ELECTRONICS

The front section of the housing contains the microprocessor and display. It is possible to adjust the display contrast via a small potentiometer on the board. The display contrast is shown below and this can be adjusted for optimum contrast.

Adjacent to this control is a reset switch, which can be used to reset the microprocessor. Note that pressing this button will reset all setup parameters.



## **36 Installation**

### **7.5 WIRING**

When connecting the Model 120, it is good practice to use shielded cable. The shield should be connected to earth at one end of the cable. The other end of the shield should not be connected.

This wiring practice is mandatory in order to comply with the requirements for Electromagnetic Compatibility as per EMC-Directive 2014/30/EU of the Council of the European Community.

### **7.6 MAINTENANCE**

All printed circuit boards must be repaired by Contrec Manufacturing Ltd.



## 7.7 TERMINAL DESIGNATIONS

### *4-20mA Input*

3	4-20mA (-)
4	4-20mA (+)

### *Outputs*

1	Low-low Alarm (-)
2	Low-low Alarm (+)
5	Low Alarm (-)
6	Low Alarm (+)
7	High Alarm (-)
8	High Alarm (+)
9	High-high Alarm (-)
10	High-high Alarm (+)

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