Model 515 Flow Computer

Operation Manual

Application BC03

Dual Stage Batch Controller
for
Mass Frequency or Analog Flowmeters

contrec

23 August 2019

Model 515 Flow Computer - Operation Manual

The instructions given herein cover the general description, installation, operation and maintenance of the subject equipment. Contrec Ltd reserves the right, without prior notice, to make engineering refinements that may not be reflected in this manual.

Should any questions arise which cannot be answered specifically by this manual, they should be directed to Contrec Ltd for further detailed information and technical assistance.

Contrec Ltd will not accept any liability for either direct or consequential damages resulting from the use or misapplication of the contents of this manual.

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MADE IN BRITAIN

Safety Notice

The information in this safety notice is for the prevention of injury to personnel and damage to the instrument.

The manufacturer assumes no liability for injury or damage caused by misuse of the instrument or for modifications made to the instrument.

Qualified Personnel

The instrument must be installed, operated and serviced by persons who have been properly trained and authorised. Personnel must read and understand this manual prior to installation and operation of the instrument.

Static Hazard

The 500 series flow computer uses high speed CMOS circuitry which is sensitive to static damage. The user should observe accepted safety practices for handling electronic devices, especially during servicing. Once the unit is installed, grounded and interconnected, the chances of static damage are greatly reduced.

Voltage Hazard

Before connecting power to the instrument, ensure that the supply voltage for the AC or DC input is suitable. The AC voltage rating is as stated on the instrument rating plate. Personnel should take all due care to avoid electric shock. For safe operation it is essential to connect a mains safety earth to the A.C. power inlet. Do not operate at altitudes above 2000m.

Welding Hazard

Do not perform electric welding in close proximity to the instrument or its interconnecting cables. If welding in these areas must be performed, disconnect all cables from the instrument. Failure to do so may result in damage to the unit.

Moisture Hazard

To avoid electrical faults and corrosion of the instrument, do not allow moisture to remain in contact with the instrument.

Disconnection Device

When powered from a mains supply this unit requires the provision of a suitable mains isolation device to be accessible near to the installed instrument.

Instrument Disposal

Contrec instrumentation should not be thrown into the general waste system.

If within EU member states, this instrument should be disposed of according to the guidelines set by the WEEE (Waste Electrical and Electronic Equipment) directive 2012/19/EU. If outside of the EU, this equipment should be responsibly disposed of according to local and national regulations for EEE (Electrical and Electronic Equipment).

By not discarding of this product along with other house hold waste you are preserving natural resources and reducing waste sent to landfill and incinerators.

Remove batteries and dispose of separately (see *Disposal of Batteries*) before disposal of Contrec instrumentation.

Disposal of Batteries

Batteries have an environmental impact. Safe and responsible disposal should be undertaken.

Batteries have an environmental impact, safe and responsible disposal should be undertaken.

In all EU member states, as per Directive 2006/66/EC, batteries must not be thrown away with general waste. Contact your local environmental authority for information regarding disposal or recycling of used batteries, alternatively they can be returned directly to Contrec Ltd. for disposal.

Please Contact Contrec Ltd before returning batteries for disposal.

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Introduction

Features

- Caters for mass flow inputs from frequency or analog flowmeters
- Single or Dual stage control
- Quick access to common batch quantities
- No-flow, leakage and overflow error detection
- Remote RUN/STOP/RESET & BATCH SET functions
- Allows for square law and non-linear correction
- Storage of 1000 transactions with time and date stamp
- Selection of Detail or Basic main menu to suit operator and application
- Selection of second language and user tags
- Pulse width and scaling of pulse output
- 4-20 mA retransmission
- Selectable protocols on serial ports including Modbus RTU and Printer output
- Front panel adjustment of 8-24 V DC output voltage
- Backlit display with LCD backup

Overview

The 515 BC03 application is a dual stage batch controller for reliable measurement of preset quantities using a mass frequency or analog input. Used as a single or dual stage controller it is suitable for fast batch applications.

It provides the operator with clear local readout and can be controlled via communications in more automated systems. There is quick access to commonly used preset values directly from the front panel if access has been authorized. Overrun compensation caters for system delays such as valve closure for precise quantities.

The instrument is compatible with a wide range of flowmeter outputs, including millivolt signals, reed switches, pulse, Namur proximity switches and analog signals. Inputs can be scaled, filtered and have non-linear correction applied. Square law and cutoff points can also be applied to the analog input.

Calculations

If using the frequency input, the total and flowrate are derived from accurately measured frequency and the number of received pulses.

mass = pulses / k-factor

mass flow = frequency / k-factor

If using the analog input, to derive the flow rate the input is normalised to a value (A) between 0 and 1.

$massflow = (M_f max - M_f min)A + M_f min$

$$mass = \int (massflow \cdot \Delta t)$$

Automatic overrun compensation calculates the new valve closure point to ensure correct delivery by averaging the overrun amount from the last three complete batches.

The overrun compensation value is valid for a new preset value provided the stored overrun is less than 20% of the new preset.

Analog Input Scaling

The analog inputs in this instrument are scaled by the following general formula:

$$f(A) = P_{min} + (P_{max} - P_{min}) \cdot A^*$$

where:

P_{min} = minimum point (equivalent to offset)

P_{max} = maximum point ($P_{max} - P_{min}$ is equivalent to span)

A^* = normalised signal (0 to 1) with correction applied for a flow input

Correction Type

- LINEAR: $A^* = A$ when the instrument is not required to apply correction
- NON-LINEAR: $A^* = A_C$ when the instrument applies correction from the points in the correction table
- SQUARE: $A^* = \sqrt{A}$ when the transmitter does not have square root extraction and it must be applied by the instrument.

Displayed Information

The front panel display shows the current values of the input variables and the results of the calculations.

The instrument can be supplied with a real-time clock for storage of up to 1000 transactions with time and date stamps.

Main Menu Variables

Main Menu Variables	Default Units	Variable Type
Mass	kg	Total
Mass Flowrate	kg/min	Rate

Refer to **Available Units of Measurement** on page 84 for the list of available units.

Communications

There are two communication ports available as follows:

- COM-1 RS-232 port
- COM-2 RS-485 port (optional)

The ports are available for remote data reading, printouts and for initial application loading of the instrument.

Isolated Outputs

The opto-isolated outputs can retransmit any main menu variable. The type of output is determined by the nature of the assigned variable. Totals are output as pulses and rates are output as 4-20 mA signals. One output is standard, a second output is available as an option.

Relay Outputs

The relay outputs 1 and 2 are used to control the flow of product for each delivery. These contacts are normally open and can be used to drive external relays, valves, pump circuits etc. The advanced option provides another two relays that can be used as fully programmable alarms for any rate type variable.

Software Configuration

The instrument can be programmed to suit the particular application needs and the flexible I/O can be assigned as required. Program settings can be changed either via the front panel (depending on assigned access levels) or via the 500 Series Program Manager (500-PM software).

The 500-PM software is a free comprehensive configuration tool and resource centre that can be used to further tailored an instrument to suit specific application needs including units of measurement, custom tags and text, access levels and more.

The software is a Windows based program that is freely available from the download section of the Contrec website. The program can be used to create a custom version of an existing application to be saved for backup purposes and/or to generate a PDF of configuration report for record keeping.

The instrument stores all set-up parameters, totals and logged data in non-volatile memory with at least 30 years retention.

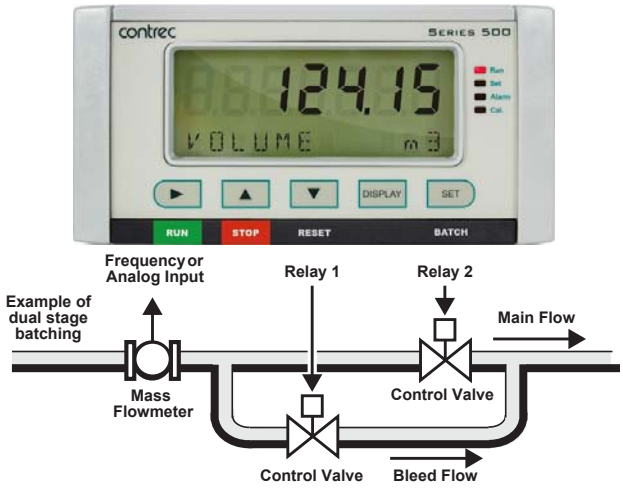


Figure 1 Typical Application Diagram

Approvals

This instrument conforms to the EMC-Directive of the Council of European Communities 2014/30/EU, the LVD safety directive 2014/35/EU and the following standards:

- *EN61326:2013* Electrical equipment for measurement, control and laboratory use – EMC requirements: Industrial Environment.
- *EN61010:2010* Safety requirements for electrical equipment for measurement, control, and laboratory use.

In order to comply with these standards, the wiring instructions in **Chapter 3 - Installation** must be followed.

FCC Declaration

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, might cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at his own expense.

Properly shielded and grounded cables and connectors must be used in order to meet FCC emission limits. Contrec Ltd is not responsible for any radio or television interference caused by using other than recommended cables and connectors or by unauthorized changes or modifications to this equipment. Unauthorized changes or modifications could void the user's authority to operate the equipment.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device might not cause harmful interference, and (2) this device must accept any interference received, including interference that might cause undesired operation.

Chapter 2
Specifications

Specification Table

Operating Environment

Temperature	-20°C to +60°C (conformal coating) +5°C to +40°C (standard - no coating)
Humidity	0 to 95% non condensing (conformal coating) 5% to 85% non condensing (no coating)
Power Supply	100-240 V AC (+/-10%) 50-60 Hz (+/-10%) or 12-28 V DC
Consumption	6W (typical)
Protection	Sealed to IP65 (Nema 4X) when panel mounted
Dimensions (panel option)	147mm (5.8") width 74mm (2.9") height 170mm (6.6") depth (behind the panel)

Display

Type	Backlit LCD with 7-digit numeric display and 11-character alphanumeric display
Digits	15.5mm (0.6") high
Characters	6mm (0.24") high
LCD Backup	Last data visible for 15min after power down
Update Rate	0.3 second

Non-volatile Memory

Retention	> 30 years
Data Stored	Setup, Totals and Logs

Approvals

Interference	CE compliance
Enclosure	IECEx, ATEX and CSA approved enclosures available for hazardous areas

Real Time Clock (Optional)

Battery Type	3 volts Lithium button cell (BR2032 for extended temperature range) (CR2032 for standard temperature range)
Battery Life	5 years (typical)

Frequency Input (General)

Range	0 to 10kHz
Overvoltage	30V maximum
Update Time	0.3 sec
Cutoff frequency	Programmable
Configuration	Pulse, coil or NPS input
Non-linearity	Up to 10 correction points

Pulse

Signal Type	CMOS, TTL, open collector, reed switch
Threshold	1.3 volts

Coil

Signal Type	Turbine and sine wave
Sensitivity	15mV p-p minimum

NPS

Signal Type	NPS sensor to Namur standard

Analog Input (General)

Overcurrent	100mA absolute maximum rating (30mA for 4-20mA inputs)
Update Time	< 1.0 sec
Configuration	4-20mA, 0-5V and 1-5V input
Non-linearity	Up to 20 correction points (some inputs)

4-20mA Input

Impedance	100 Ohms (to common signal ground)
Accuracy	0.05% full scale (20°C) 0.1% (full temperature range, typical)

0-5 or 1-5 Volts Input

Impedance	10MOhms (to common signal ground)
Accuracy	0.05% full scale (20°C) 0.1% (full temperature range, typical)

Logic Inputs

Signal Type	CMOS, TTL, open collector, reed switch
Overvoltage	30V maximum

Relay Output

No. of Outputs	2 relays plus 2 optional relays
Voltage	250 volts AC, 30 volts DC maximum (solid state relays use AC only)
Current	Maximum 3A EMR, 1A SSR

Communication Ports

Ports	COM-1 RS-232 port COM-2 RS-485 port (optional)
Baud Rate	2400 to 19200 baud
Parity	Odd, even or none
Stop Bits	1 or 2
Data Bits	8
Protocols	ASCII, Modbus RTU, Printer*

Transducer Supply

Voltage	8 to 24 volts DC, programmable
Current	70mA @ 24V, 120mA @ 12V maximum
Protection	Power limited output

Isolated Output

No. of Outputs	1 configurable output (plus 1 optional)
Configuration	Pulse/Digital or 4-20mA output

Pulse/Digital Output

Signal Type	Open collector
Switching	200mA, 30 volts DC maximum
Saturation	0.8 volts maximum
Pulse Width	Programmable: 10, 20, 50, 100, 200 or 500ms

4-20mA Output

Supply	9 to 30 volts DC external
Resolution	0.05% full scale
Accuracy	0.05% full scale (20°C) 0.1% (full temperature range, typical)

Important: Specifications are subject to change without notice.
Printer protocol is available only if RTC option is installed.

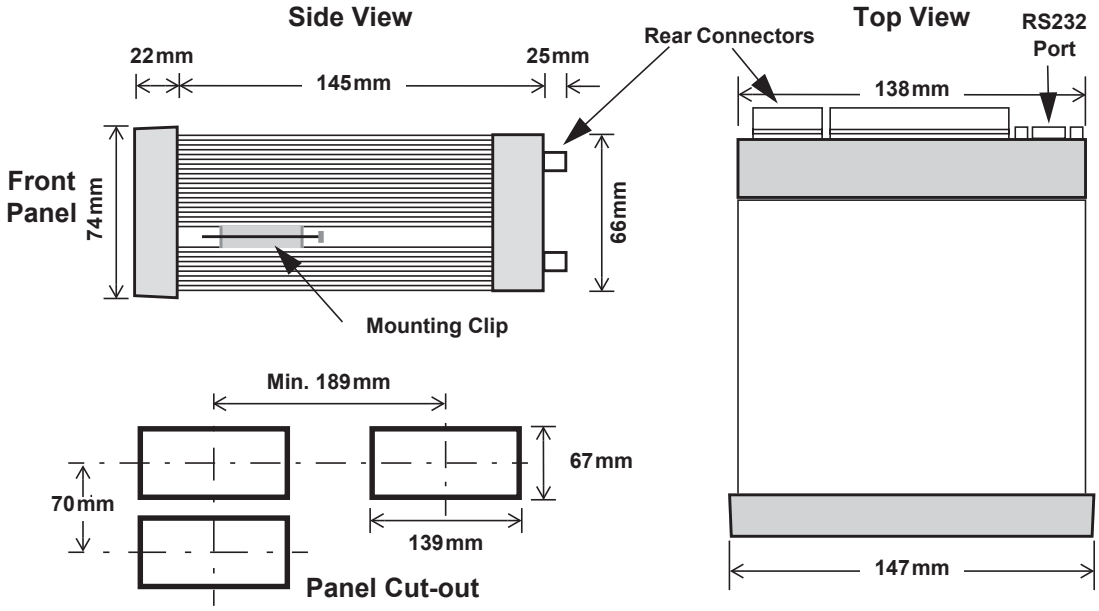
Chapter 3
Installation

Panel Mounting

The instrument should be located in an area with a clean, dry atmosphere that is also relatively free of shock and vibration.

The standard mounting procedure is panel mounting in a cutout that is 139 mm wide by 67 mm high. Two side clips secure the unit into the panel.

shows the panel mounting requirements for the 500 Series Instrument.



500 Series Instrument Panel Mounting

Electrical Connection

Rear Panel Connections

Figure 2 shows the connections on the rear panel of the instrument.

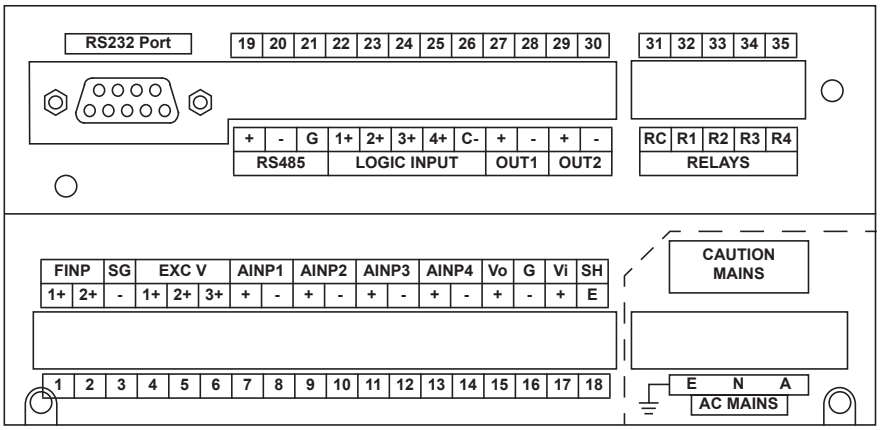


Figure 2 Rear Panel Connections

Terminal Designations

Terminal Label			Designation	Comment
1	FINP	1+	Frequency Input 1+	Mass Flow Input
2	FINP	2+	Frequency Input 2+	Not used
3	SG	-	Signal ground	
4	EXC V	1+	Excitation Term 1+	Not used
5	EXC V	2+	Excitation Term 2+	Not used
6	EXC V	3+	Excitation Term 3+	Not used
7	AINP1	+	Analog Input ch 1 (+)	Not used
8		-	Analog Input ch 1 (-)	
9	AINP2	+	Analog Input ch 2 (+)	Not used
10		-	Analog Input ch 2 (-)	
11	AINP3	+	Analog Input ch 3 (+)	Mass Flow Input
12		-	Analog Input ch 3 (-)	
13	AINP4	+	Analog Input ch 4 (+)	Not used
14		-	Analog Input ch 4 (-)	
15	Vo	+	8-24 volts DC output	Overload protected
16	G	-	DC Ground	
17	Vi	+	DC power input	DC power in 12-28V
18	SH	E	Shield terminal	
E	AC MAINS	E	Mains ground	AC power in 100-240VAC
N		N	Mains neutral	
A		A	Mains active	

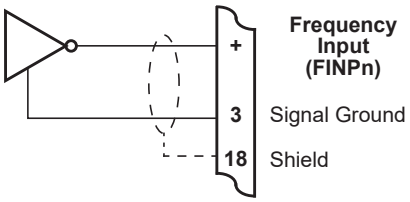
Terminal Label			Designation	Comment
19	RS485 COM-2 port	+	RS485 (+)	Optional RS485 port
20		-	RS485 (-)	
21		G	RS485 ground	
22	LOGIC INPUTS	1+	Switch 1	Remote Run
23		2+	Switch 2	Remote Stop/Reset
24		3+	Switch 3	Remote Set
25		4+	Switch 4	CAL Switch – In field access protection
26		C-	Signal ground	
27	OUT1	+	Output ch 1 (+)	
28		-	Output ch 1 (-)	
29	OUT2	+	Output ch 2 (+)	Optional output
30		-	Output ch 2 (-)	
31	RELAYS	RC	Relay common	
32		R1	Relay 1	Single Stage Control
33		R2	Relay 2	Dual Stage Control
34		R3	Relay 3	Optional relays
35		R4	Relay 4	
RS232 COM-1 port			9-pin serial port	

Inputs

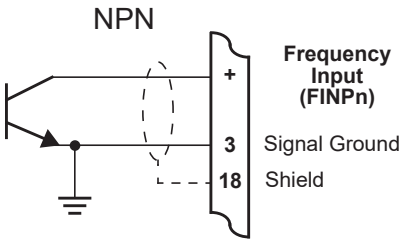
Frequency Input Connection

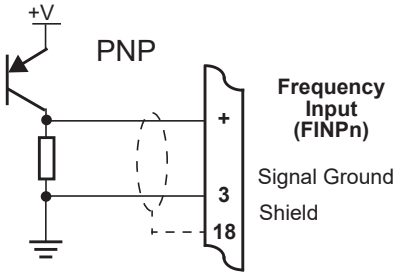
Connect pulse or frequency input signals from devices such as: TTL, CMOS, open collector, reed relay switch, coil and Namur proximity switch, as shown below. For better signal integrity, it is recommended to use shielded cable. Refer to **Terminal Designations** on page 10 for specific terminal numbers for this application.

Squarewave, CMOS or TTL

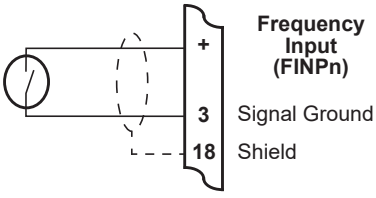


Open Collector

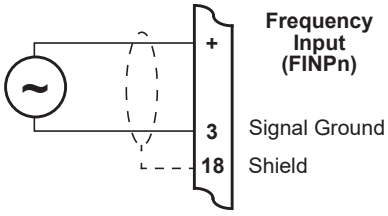




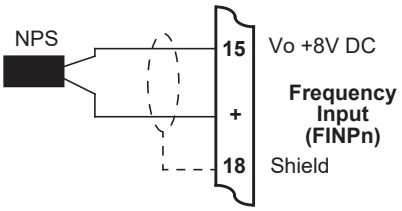
Reed Relay Switch



Coils - with 15 millivolts peak to peak AC minimum



Namur Proximity Switch



Analog Input Connections

All analog inputs can accept DC signals ranging from 0-5V, 1-5V and current signals from 4 to 20mA.

CAUTION

Applying levels of input current above the absolute maximum rating (100mA or 30mA for 4-20mA inputs) may cause permanent damage to the input circuitry.

0-5 and 1-5 Volt Inputs

For externally powered voltage transmitters, connect each transmitter to a pair of input terminals as shown in Figure 3. Refer to **Terminal Designations** on page 10 for specific terminal numbers for this application.

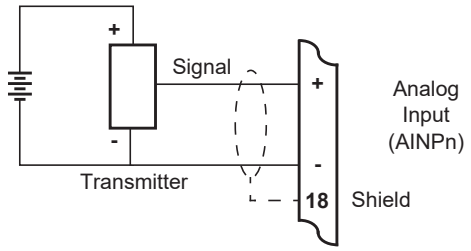


Figure 3 Externally Powered Voltage Transmitter

Connect internally powered voltage transmitters as shown in Figure 4.

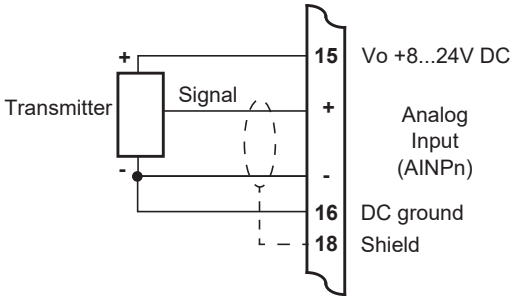


Figure 4 Internally Powered Voltage Transmitter

4-20mA Inputs

For externally powered current loops, connect each transmitter to a pair of input terminals as shown in Figure 5. Refer to for specific terminal numbers for this application.

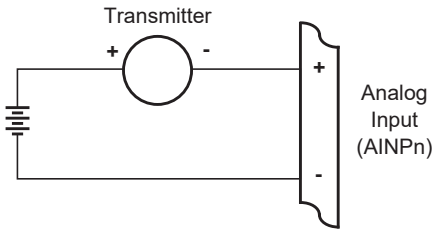
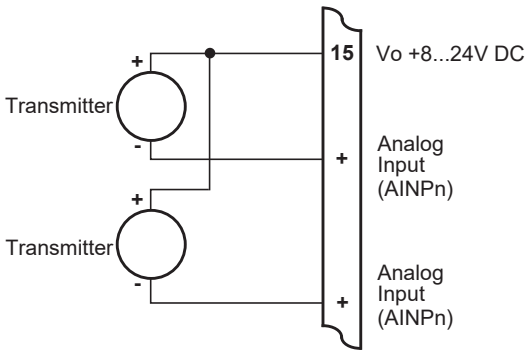


Figure 5 Externally Powered Current Loop

The internal overload-protected power supply has sufficient power for three current loops at 24 V DC (more current loops can be supplied by using a reduced voltage setting). Connect internally powered current loops as shown in Figure 6.

Figure 6 Internally Powered Current Loops



Logic Input Connection

These input(s) are designed to be connected to CMOS, TTL, open collector signals or a voltage free contact switch. A minimum activation time of 300ms is required to guarantee reading of an input.

It is possible to read the status of all the logic inputs via a Modbus register even if they are not used for a control purpose in the application.

A remote push-button key can be connected to the Logic Inputs as shown below. **Logic Input Control** on page 26 describes the function of the inputs.

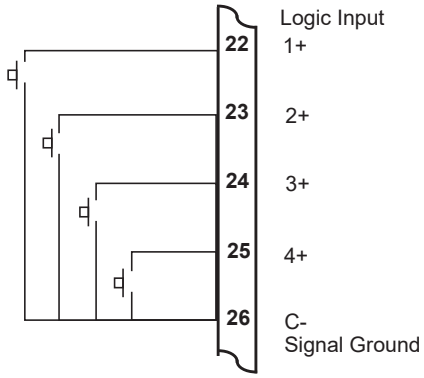


Figure 7 Logic Inputs Connection Diagram

Outputs

The advanced option for the instrument provides two opto-isolated output ports. Either or both can be used for 4-20 mA or pulse outputs.

CAUTION

Due to the dual-purpose nature of the outputs, take care not to set the output as an open collector pulse type signal when connected to a 4-20 mA loop circuit.

4-20 mA Output Connection

Figure 8 shows the connections for a 4-20 mA output. Output channel 1 uses terminals 27 (+) and 28 (-), output channel 2 uses terminals 29 (+) and 30 (-).

Maximum Load Resistance = (Supply-9) / 0.02 ohms

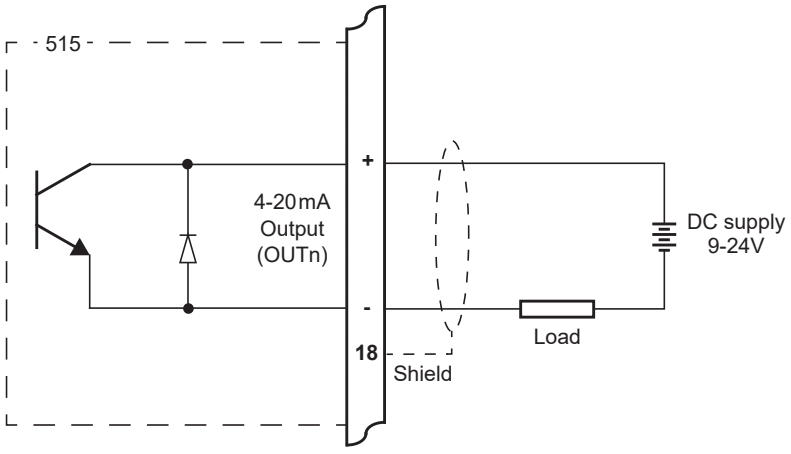


Figure 8 Output 4-20 mA Connection Diagram

Digital Output Connection

Figure 9 shows a connection example for a pulse output. Output channel 1 uses terminals 27 (+) and 28 (-). Output channel 2 uses terminals 29 (+) and 30 (-).

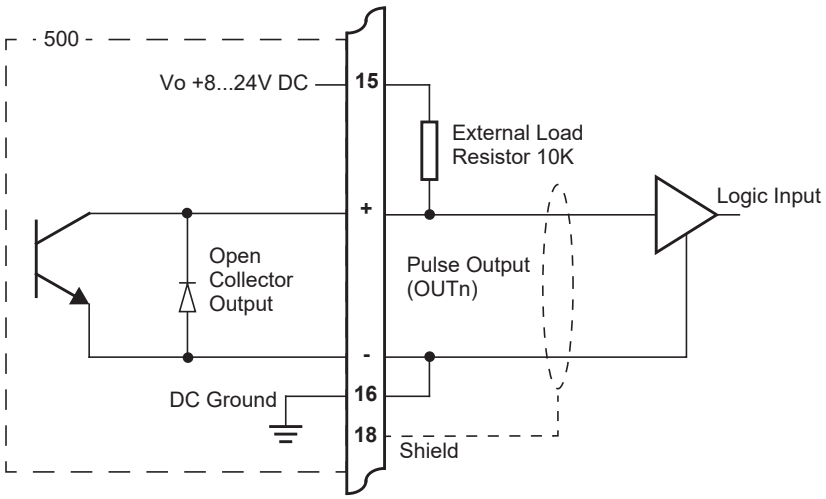


Figure 9 Output Pulse Connection Diagram

Control Relays (Alarms)

The standard instrument has two relays, which are used for the dual stage batch control. The relays can drive external devices such as valves, pump circuits or external relays.

The advanced option has two extra relays that can be freely assigned as alarm relays. The operation of alarm relay(s) can be set to various modes as described in **Alarms** on page 48.

There is also an equipment failure alarm option. This alarm can have normally closed (open) contacts which open (close) when the instrument displays any error message as listed in **Error Messages** on page 56, or if there is a loss of power to the instrument.

The output characteristics of the relays are:

Maximum Voltage	30 volts DC or 250 volts AC
Maximum Current	3 A for EMR, 1A for SSR

Note: Solid state relays (SSR) use AC voltage only.

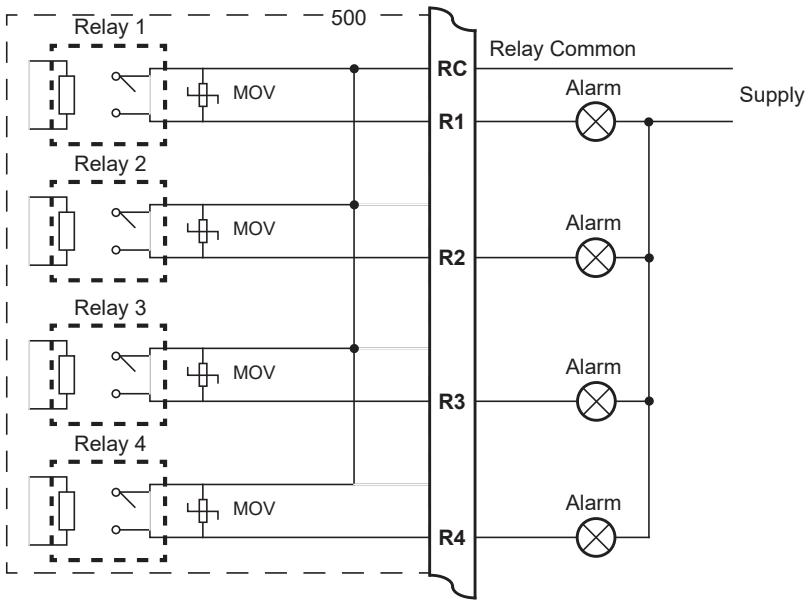


Figure 10 Relay Connection Diagram

RC Network for Interference Suppression

When driving inductive loads with the relay outputs, it is recommended to use RC suppression networks (often called “Snubbers”), fitted at the load end, for the following reasons:

- To limit the amount of electrical noise caused by arcing across the contacts, which may, in extreme cases, cause the microprocessor to act erratically or cause other unwanted interference with connected signals.
- To protect the relay contacts against premature wear through pitting or SSR (where specified) against premature failure.

RC suppression networks consist of a capacitor and series resistor and are commonly available in the electrical industry. The values of R and C are dependent entirely on the load. However, if the user is unsure of the type of snubber to use, values of 0.25 µF and 100 Ω will usually suffice. Note that only UL and mains approved RC suppression networks should be used.

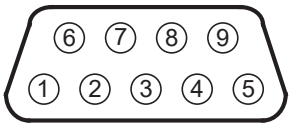
The basic principle of the operation is that the capacitor prevents a series of sparks arcing across the contact as the contact breaks. The series resistor limits the current through the contact when the contact first makes.

Communications

The communication protocols are described in **Communications** on page 59.

COM-1 RS-232 Port

The COM-1 RS-232 port has a 9-pin DB female connector and has the following pinout:



Pin 1	Not used
Pin 2	Transmit (TxD)
Pin 3	Receive (RxD)
Pin 4	Not used
Pin 5	Ground
Pin 6	Not used
Pin 7	Handshake line (CTS)
Pin 8	RTS Out
Pin 9	Not used

Note: The instrument does not require a null-modem cable for connection to a personal computer. Refer to **Hardware Interconnection** on page 59 for cable termination requirements.

COM-2 RS-485 Port (Optional)

Up to 32 units can be connected to a common RS-485 bus. Each unit has a unique address that the host computer uses to identify each instrument.

Figure 11 shows the connection of several instruments to a computer using the RS-485 port.

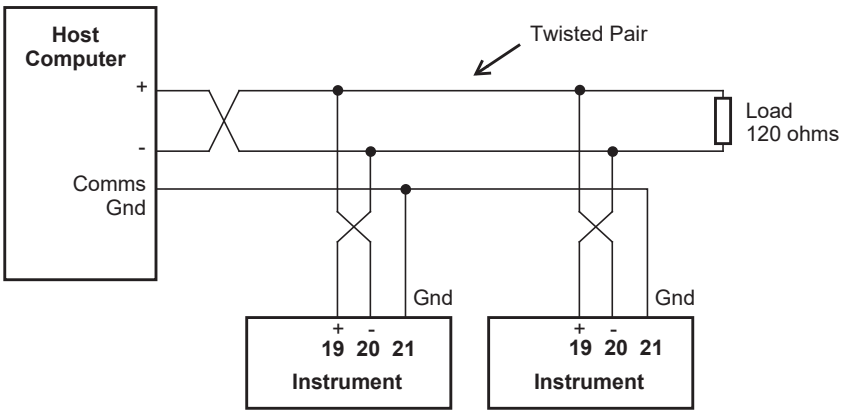


Figure 11 RS-485 Interface Connections

Earthing and Shielding

It is a good practice to use shielded cable for all signal connections to the instrument. Care must be taken to separate signal cables from power cables to minimize interference.

Overall earth should be connected at the instrument end only. This connection should be as short as possible and connected to the earthing point on the rear terminal at pin 18.

Chapter 4
Operation

Front Panel Operation

In normal operation, press the buttons on the front panel to control the operation of the batch controller or to display the values recorded and calculated by the instrument.

There are several categories of information that the instrument can display:

- Totals
- Rates
- Batch preset values
- Instrument settings

For each total, there is an associated rate as follows:

Total	Rate
Mass	Mass Flowrate

Default Variable

In some applications, a particular variable is of more interest than others, and for this reason a default variable can be assigned during instrument calibration. The default variable is used in the following ways:

- Determines what the display returns to when the Stop key is pressed while viewing other items in the main menu list.
- Determines what the display returns to if the display timeout option is enabled and no buttons are pressed for the selected period (usually 30 seconds).
- Determines what is displayed on power up or exit of Calibrate mode.

Status LEDs

The status LEDs illuminate to show the following conditions:

Run Solid led: The instrument has a batch in progress.
Fast flashing led: Batch paused.
Slow flashing led: Waiting for valves to close.
Set Solid led: The instrument is in Calibrate Set mode.
Flashing led: Count down to automatic restart of next batch.
Alarm The instrument has an error, as indicated on the display panel.
Cal The instrument is in Calibrate View mode.

Front Panel Keys

RUN Press the **RUN** key to start or resume a batch. The run led will illuminate.

STOP Press the **STOP** key to halt a current batch. The instrument will go into pause mode and the run led will flash at a steady pace. The incomplete batch can be resumed or the **STOP** key can be held again to end the batch and the run led will turn off. The **STOP** key is also used to stop the next batch if in automatic restart count down, can be used to return the display directly to the default variable (total) when scrolling through the main menu items and can be used to acknowledge flow errors without resetting the total.

RESET Use the **RESET** key to step directly to the HOLD.SET - TO RESET prompt within the main menu items. Holding SET at this point will clear the batch totals or the DISPLAY key can be pressed to step onto the HOLD.SET - TO PRINT prompt if the printer option has been selected.

The instrument makes three beeps when it resets the totals and two beeps when a printout is started.

DISPLAY Press the DISPLAY key to step or scroll through the main menu items.

BATCH Hold the **BATCH** key to display the current batch preset value. Continue to hold for two seconds to enter edit mode for the preset if access is authorised. Pressing the **BATCH** key briefly displays the accumulated total.

Main Menu Items

The main menu in this instrument consists of the following items. The DISPLAY key is used to step or scroll through the list. The full menu can only be viewed if the batch controller has been stopped and reset .

DISPLAY ↓	Description	Options
MASS	Mass	Hold the SET key to display (or edit) the batch preset or briefly press to view the accum total
FLOW	Mass flowrate	
TO RESET		Hold the SET key to manually reset the current delivery (batch) total.

DISPLAY ↓	Description	Options
TO PRINT	Only shown if print option is selected	Hold the SET key to manually print a delivery docket.
REPORT PRINT	Only shown in Detail Menu if print option is selected	Hold the SET key to print log report as defined in the TM/LOG section of calibration.
LOGGED DATA	Only shown in Detail Menu if real-time clock option is installed	Hold the SET key to display data logs as described in **Data Logs** on page 22.
MODEL INFO	Only shown in Detail Menu	Hold the SET key to display the Model information as described in **Model Information** on page 24.
CAL MENU	Only shown in Detail Menu	Hold the SET key to enter Calibration View mode as described in **Calibration View Mode** on page 30.

Detail and Basic Menu

The 515 instrument has the option to switch the main menu from the full Detail menu to a Basic menu. The Detail menu includes all of the main menu variables and the HOLD SET sub menu items as listed above. In the Basic menu only the application or operator essential main menu variables are shown. The main menu variables to be shown in the basic menu need to be selected in the 500 Series Program Manager prior to the application software being downloaded to the instrument. The 500 Series Program Manager (500-PM) is Windows based configuration and resource tool for the 500 Series and is freely available from the www.contrec.co.uk website.

To switch between the Detail and Basic menu, while in the main menu, press and hold the DISPLAY and SET keys together for 5 seconds. When switching to the Detail menu the display will briefly show:
dISPLAY DETAIL MENU.
When switching to the Basic menu the display will briefly show:
dISPLAY BASIC MENU.

When the application software is first installed, the default is the Detail menu. From that point, the menu type is saved and restored on power cycle. The menu type will need to be Detail to access the CAL MENU

Setting the Batch Preset

SET The batch preset can only be set while the instrument is in the non-operational state, i.e. batch is complete or has been stopped and reset. Hold the SET key to display the current preset value while viewing the total variable. The display of the preset will change from view mode to edit mode after 2 seconds if access has been enabled in calibration. Once in edit mode the **Set** indicator will illuminate and the preset value can be changed in the same way as in calibration set mode, see **Changing Numeric Settings** on page 32. The SET key is used to exit edit mode.

Limit on Batch Size

To prevent accidental entry of large batch quantities, a maximum batch limit can be programmed during calibration. The operator is then prevented from entering a batch quantity which exceeds this value.

Common Preset Values

If the batching application continually uses a regular set of preset values then quick access can be provided to these. In calibration, there is the opportunity to enter up to 10 commonly used preset values.

These can then be accessed whilst in batch edit mode (described above) by pressing the DISPLAY key. The pre-programmed values will appear in the order they were entered in calibration. The display will step through the presets back to the currently entered value which can still be manually edited. While displaying the desired preset value, press the SET key to accept the value and exit edit mode.

Data Logs

The instrument will log up to 1000 deliveries (batches) if the real-time clock option is installed. The logs are taken at the end of each batch or upon reset if a batch has been aborted before the preset total has been reached. Each entry has a log number, a delivery number and a time and date stamp.

When the number of log entries exceeds 999 the oldest log entry is overwritten by the newest one.

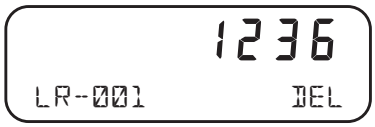
View Data Logs

Use the following procedure to view the data that has been logged by the instrument:

1. Press the DISPLAY key to scroll through the menu to the LOGGED DATA prompt.

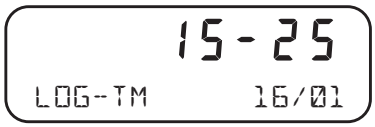
2. Hold the SET key.

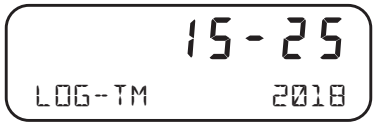
The system displays the most recent log record first. The log record number and corresponding delivery number are shown, for example LR-001 and DEL 1236.



3. Use the ▲ or ▼ keys to scroll to the delivery number or log record of interest.
4. Press the DISPLAY key to show the information stored in the selected log record. Each log record consists of:
   - time and date stamp,
   - error code
   - totals for the delivery.
5. While holding the DISPLAY key use the ▶ key to step through the stored information.
6. While holding the DISPLAY key use the RESET key to print the data for the displayed log if the printer option has been selected.

The following example shows the format of the time and date stamp at 15:25 (3:25 pm) on 16 January 2018. The day and month alternate with the year in the bottom right hand corner.





Model Information

The model information items display the hardware, software and application versions of the instrument. This information is mainly for service personnel. Typical examples are shown below.

DISPLAY ↓	Description
2- 1- - 5- 515 MODEL	The hardware model information. Refer to **Product Codes** on page 81 for full information.
F- BC03 INPUT	The Application number and the assignment of the inputs. Refer to **Application Information Code** on page 82 for more information.
3_0_000 500PM VERS	The version of 500-Series Program Manager from which the application software was compiled.
026357 CUSTOM VERS	The Customer version code for this installation. Refer to **Custom Version Codes** on page 82 for more information.
123456 ABC123 S/N	The instrument serial number and unit tag. The serial number is on the top line and unit tag is on the bottom left. Both items are entered when the instrument application software is initially loaded. If the unit tag is not used the default tag, UNIT, will be used.
16- 15 EDITED 27/08 2018	The time and date when the calibration of the instrument was last edited. The format of the time and date is the same as for the data logs. This example shows 16:15 (4:15pm) on the 27th August 2018. This function is available only if the instrument has the real time clock option.
5 POWER CYCLE	The number of power cycles that have occurred since the application software was installed.
1 WDT RESET	The number of 'watchdog timer' (WDT) resets that have occurred since the application software was installed. The WDT Reset count is only shown if a WDT Reset has occurred.
HOLd.PSt CONFIG PRINT	If the printer protocol is assigned to one of the communication ports, the prompt to print the full program configuration report will be shown. Hold Reset to start the printing of the configuration report. The report will be in a similar format to the report generated by the 500 Program Manager.

Press SET at any time to exit from the Model information.

Batch Operation

Starting a Batch

The delivery (batch) will start when the **RUN** key is pressed. The RUN led will illuminate and the instrument will begin to totalise from zero or, if programmed for count down mode, the display will decrement from the preset quantity.

The batch controller's two relays can be used to control the delivery of product. These are energised and de-energised as described below.

Stopping a Batch

The delivery (batch) can be stopped at any time by pressing the **STOP** key. Once the process has been interrupted in this way it can be continued (if the **STOP** key functionality is programmed to PAUSE) by pressing the **RUN** key or the batch can be stopped completely by holding the **STOP** key until the run led turns off.

When the process is in pause mode, the RUN led will flash to prompt the operator to restart or abort the batch.

Resetting a Batch

The instrument can be programmed to reset by different means.

- After the end of a batch, the **RESET** key can be pressed to step directly to the HOLD.SET - TO RESET prompt in the main menu list. Holding the SET key at this point will reset the batch total. If the instrument is programmed to count down, the display will revert to the preset value. If it is programmed to count up, the batch total will clear to zero. The next batch cannot be started until the previous batch total has been reset.
- If Auto Reset is enabled in the parameters section of calibration, the batch total will automatically reset when the next delivery (batch) is started.

Printing a Delivery Docket

If the print option has been enabled, a delivery docket can be printed by different means. The print prompt can only be accessed or a printout initiated if there is no delivery or batch in progress.

- If the AUTO PRINT feature has been Enabled in the TM/LOG menu, a delivery docket will automatically be printed at the end of each batch at the same time that the delivery is logged. End of batch occurs when a batch ends normally or if a batch is manually ended.
- The HOLD.SET - TO PRINT prompt in the main menu can be used to initiate a delivery docket. The DISPLAY key can be used to scroll through the main menu items or the RESET/PRINT key can be used to step directly to the HOLD.SET - TO RESET prompt and then a single press of the DISPLAY key will step onto the print prompt. If an original printout has already been printed, a subsequent delivery docket will include the text “(DUPLICATE DOCKET)”.
- Previous (logged) delivery transactions can be reprinted from within the LOGGED DATA menu by scrolling to the desired DEL number, then while holding the DISPLAY key, press RESET (PRINT) key to initiate a reprint.

Logic Input Control

This instrument allows for remote operation via the logic inputs on the rear terminals. The logic input have the following functions:

- Logic Input 1 - Remote Run
- Logic Input 2 - Remote Stop/Reset
- Logic Input 3 - Reserved
- Logic Input 4 - CAL Switch - In field access protection

The Remote Stop input can also be used to reset the batch total by holding the logic input low for 2 seconds if the batch is already complete.

For connection details, refer to **Logic Input Connection** on page 13.

Batch Flow Errors

The instrument has the ability to raise an alarm when it detects a loss of flow, a quadrature input error, an unexpected/overflow or a leakage in the system.

- **No Flow Error** - The no flow condition is detected when the flow timeout expires during a delivery. There must not be a period of no flow greater than the timeout value during the delivery.
- **Unexpected/Over Flow Error** - The overflow condition is detected when the flow continues longer than the timeout period after the controller has attempted to stop (or pause) the flow.
- **Leakage Error** - The leakage condition is detected when an amount greater than the acceptable total is received without flow being initiated by the batch controller.

The point at which these errors are detected is dependant on the values programmed into the calibration parameters such as Batch Flow Timeout and Acceptable Total. The open collector outputs can be assigned to activate whenever one of the flow errors occur. Refer to **Instrument Settings** on page 36 for more details.

A ‘No Flow’ or ‘Unexpected/Over Flow’ error can be cleared by pressing the STOP key without resetting the totals. A paused batch may be restarted or the delivered total remain until a reset action is carried out.

If logging and/or printing is enabled, the highest priority Error/Exception that occurred during the batch will be included as part of the recorded data. Refer to **Error Messages** on page 56 for details on the order of priority.

Batch Control Processes

The batch controller can be programmed to operate in various ways including:

- Manual Reset (manual start).
- Automatic Reset (manual start).
- Automatic Restart for continuous batches.

In each of the above modes and configurations the parameters can be programmed to determine the behaviour and timing of relays and output signals. The following figures provide examples of some batch operations. Refer to **Instrument Settings** on page 36 for more details.

Manual and Automatic Reset

If Manual Reset the **RESET** key must be pressed at the end of the batch to clear the batch total. This must be done before another batch can be started. If Automatic Reset is programmed, a new batch is commenced each time the **RUN** key is pressed.

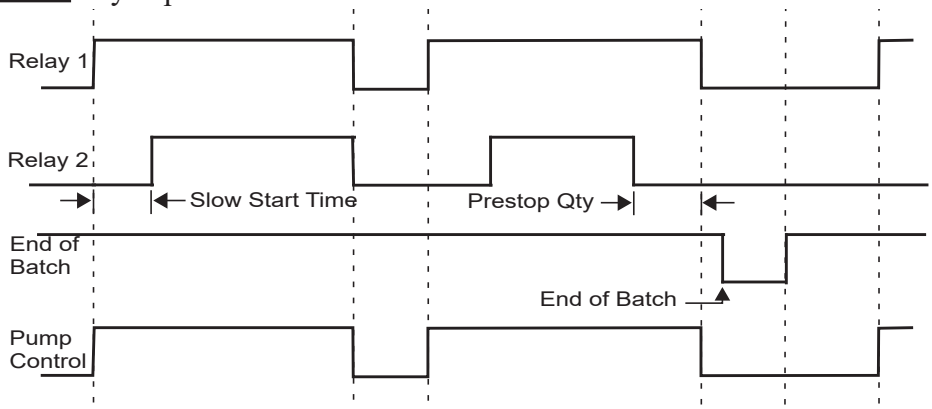


Figure 12 Batch Operation with Manual or Automatic Reset

Automatic Restart

If Automatic Restart is enabled the next batch will commence automatically when the restart timer expires after the end of batch has occurred. The SET led will flash while the instrument is waiting to automatically restart.

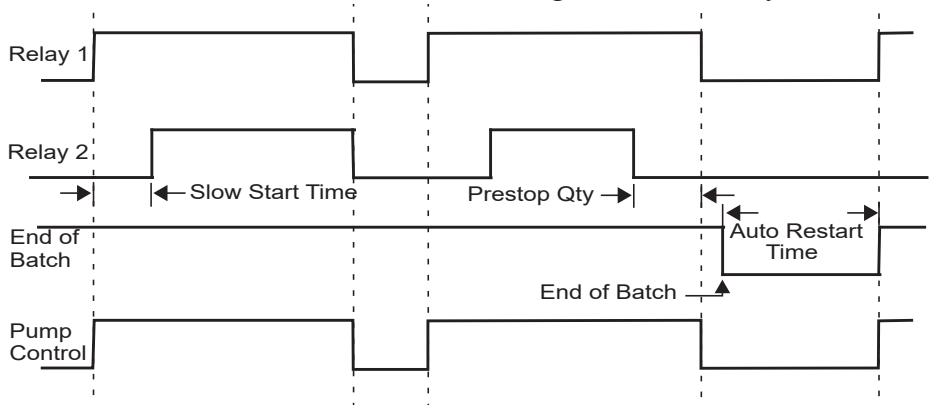


Figure 13 Batch Operation with Automatic Restart

Chapter 5
Instrument Calibration

Introduction

The 500 Series instrument calibration settings can be programmed via the front panel, according to program access levels explained below, or via the 500 Series Program Manager - a freely available Windows based configuration and resource tool.

After an instrument has been configured by either means to suit the application requirements, the settings can be recorded or application software backups or instrument clones created as explained further in **Program Backup & Reports** on page 33.

You can view or change the settings of the instrument according to the access level for each parameter, as set by the 500 Series Program Manager. There are five levels of access to the parameters as follows:

- **Not visible** - you cannot display or edit the parameter.
- **Display only** - you can display the parameter, but you cannot change the setting.
- **Programmable** - you can change the setting of the parameter in Calibration Set mode.
- **Password protected** - you can change the setting of the parameter in Calibration Set mode only if you enter the correct password.
- **CAL switch protected** - you can change the setting of the parameter in Calibration Set mode only if you enter by using the CAL switch on Logic Input 4 to accept the password.

Note: When you enter Calibration Set mode, the instrument prompts to enter a password. Any value will allow to change the settings of the "programmable" parameters, but the correct password must be entered to change the password-protected parameters. Likewise, the CAL switch (Logic Input 4) must be used to accept the password to change the CAL switch protected parameters.

Calibration View Mode

Use the following procedure to view the calibration settings of the instrument:

1. Press DISPLAY to scroll to the CAL MENU prompt.
2. Hold the SET key.

The instrument beeps once, illuminates the **Cal** indicator and shows CAL on the display panel.

- Press ▶ to scroll through the flashing menu headings.
- Press SET to scroll through submenu items.
- Hold DISPLAY to return to the main calibration menu.

3. To exit from the Calibration View mode, press ▶ to scroll to the END option and press SET.

   The instrument returns to Normal Operation mode.

Calibration Set Mode

In Calibration Set mode, you can change the settings of the "programmable" parameters. You must enter the system password to change the setting of the "password-protected" parameters and you must use the CAL switch on Logic Input 4 to access the "Cal switch protected" parameters.

Use the following procedure to enter Calibration Set mode:

1. Press DISPLAY to scroll to the CAL MENU prompt.
2. Hold the SET key.

The instrument beeps once, illuminates the **Cal** indicator and shows CAL on the display panel.

3. Press ▶ to select any flashing menu heading except END.
4. Hold SET for two seconds.

   The instrument requests a password.

5. Press ▲ or ▼ to change the value of the current digit. To select the next digit, press ▶.

6. Press SET or use the CAL switch on Logic Input 4 to accept the password.

- If the CAL switch is used and the password is correct, the instrument makes two beeps and displays message:
  -Edit- CS_PW MODE
  and enables you to change "programmable", "password protected" and "CAL switch protected" parameters.
- If the CAL switch is used but the password is incorrect, the instrument makes one beep and displays message:
  -Edit- CAL_SW MODE
  and enables you to change "programmable" and "CAL switch protected" parameters.
- If the SET key is pressed and the password is correct the instrument makes two beeps and displays the message:
  -Edit- PASSW MODE
  and enables you to change the "programmable" and "password-protected" parameters.
- If the SET key is pressed and the password is incorrect the instrument makes one beep and displays the message:
  -Edit- PROG MODE
  and enables you to change only the "programmable" parameters.

Run
Set
Alarm
Cal

The instrument illuminates both the **Cal** and **Set** indicators.

7. Edit the instrument parameters as required. The programmable values are indicated by the flashing display.

- To change a numerical value, press ▲ to increase a value, or press ▼ to decrease a value. Press a key momentarily to change the value one number at a time. Hold a key to scroll through the numbers. To proceed to next digit, press ▶.
- To change an option setting, press ▲ or ▼ to scroll through the options.

8. Press SET to accept the currently displayed value and proceed to the next parameter. You can press DISPLAY to briefly view the current edit mode: -Edit- XXXXXX MODE, as described in step 6 above.
Continue to hold the DISPLAY key to return to the main calibration menu.

9. To exit from Calibrate Set mode, press ▶ to scroll through the main calibration menu to END, then press SET. Otherwise, from any menu, you can press and hold SET for two seconds.

Run
Set
Alarm
Cal

The instrument makes two beeps and cancels the **Cal** and **Set** indicators.

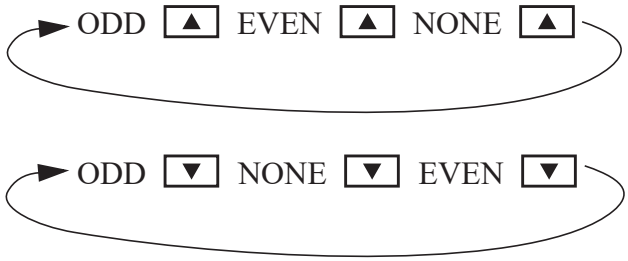
Changing the Instrument Settings

In Calibration Set mode, the display flashes the item that can be changed. For option settings, the display flashes the complete option. For a numeric parameter, the display flashes one digit at a time, you can change the value of the flashing digit as required, then move the flashing cursor to change another digit.

Note: When you change the setting of a parameter, the instrument records the result as soon as you move to another parameter, or exit from the Calibration Set mode.

Changing Option Settings

When you display an option that can be changed, the entire option flashes on the display, such as the choices of ODD, EVEN or NONE for the communications parity bit checking. Press [▲] or [▼] to change the option. You can "scroll" through the options in either direction to make a selection as shown below.



Changing Numeric Settings

The display flashes the digit that can be changed.

Press [▶] to select the digit that you wish to change.

Press [▲] or [▼] to increase or decrease the value of the selected digit.

Changing the Decimal Point

To change the position of the decimal point, press [▶] to move the flashing selection until the decimal point flashes. Press [▲] or [▼] to move the decimal point to the right or left as required.

Units of Measurement

The calibration of some parameters is based on the units that are defined for the relevant variables. These units of measurement can been viewed in the UNITS menu in calibration below.

Program Backup & Reports

Backup via 500 Series Program Manager

As well as programming the 500 Series instruments via the front panel (according to program access levels), the 500 Series Program Manager (500-PM) can be used to create a custom version of the application software and program parameters preset prior to downloading the application software. Backups of customised applications can be saved as downloadable APX or APL files and the full configuration reports printed or saved as PDF. The 500-PM is a Windows based programming tool and resource centre and is freely available from the Contrec www.contrec.co.uk website.

Instruments are often supplied from the factory with the default application software, but it is by using 500-PM software that program access levels are set, USER text and messages customised and print headers and footers entered.

Printing Configuration Report

To assist in keeping an audit trail of the program settings and changes made via the front panel, the 515 instrument provides the ability to print the configuration to a local printer if one has been connected and assigned to one of the 515 communication ports.

The prompt to hold the Reset key to print the configuration report

is found at the end of the Model Info menu, described in Model Information on page 82. The report can be lengthy and adequate printer paper must be available. (Note: This feature is available in versions 3.0.377 and later.)

Upload and Clone of Application Software

To assist in maintaining a backup for important applications and installations, the 500-Series Program Utility software (500 PM Lite) (versions 3.0.377 and later) can be used to upload the instruments application software with all of the current program settings.

The 500 PM Lite program is a Windows based computer program which can be downloaded for free from the Contrec www.contrec.co.uk website and is part of the package when the Contrec 500 Series Program Manager is installed. The 500 PM Lite provides the option to ‘Upload Application’ or ‘Upload Report Only’.

Once uploaded to the 500 PM Lite, the report can be viewed or printed. The application upload is automatically saved as an APX or APL file. The file can be used then or reopened later to download to another 515 instrument (of the same or higher class) to create a clone of the original instrument.

Calibration Menu Tree

Figure 14Figure 14 and Figure 15 show the keys for moving around the calibration menu tree in Calibration View or Set mode.

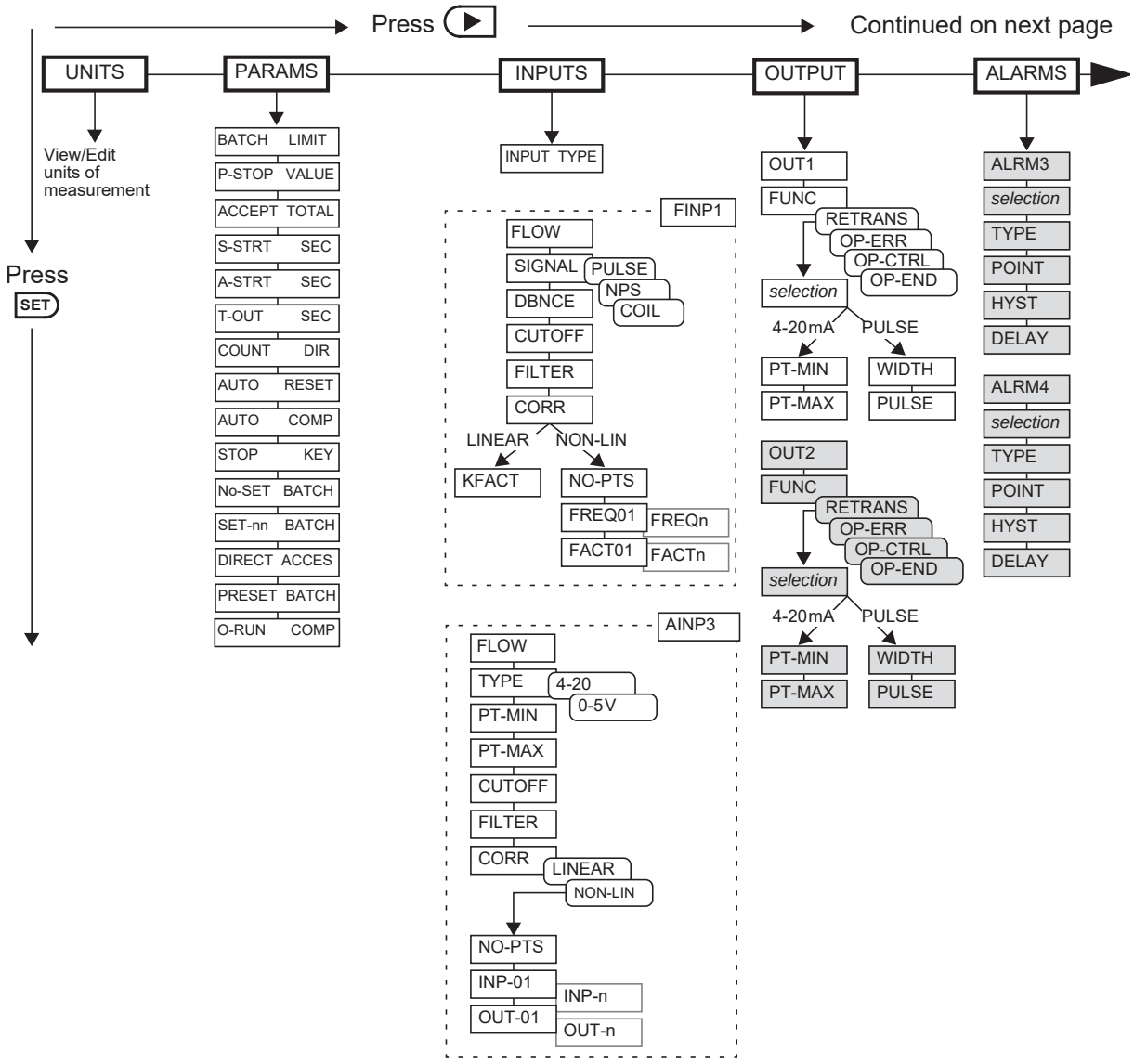
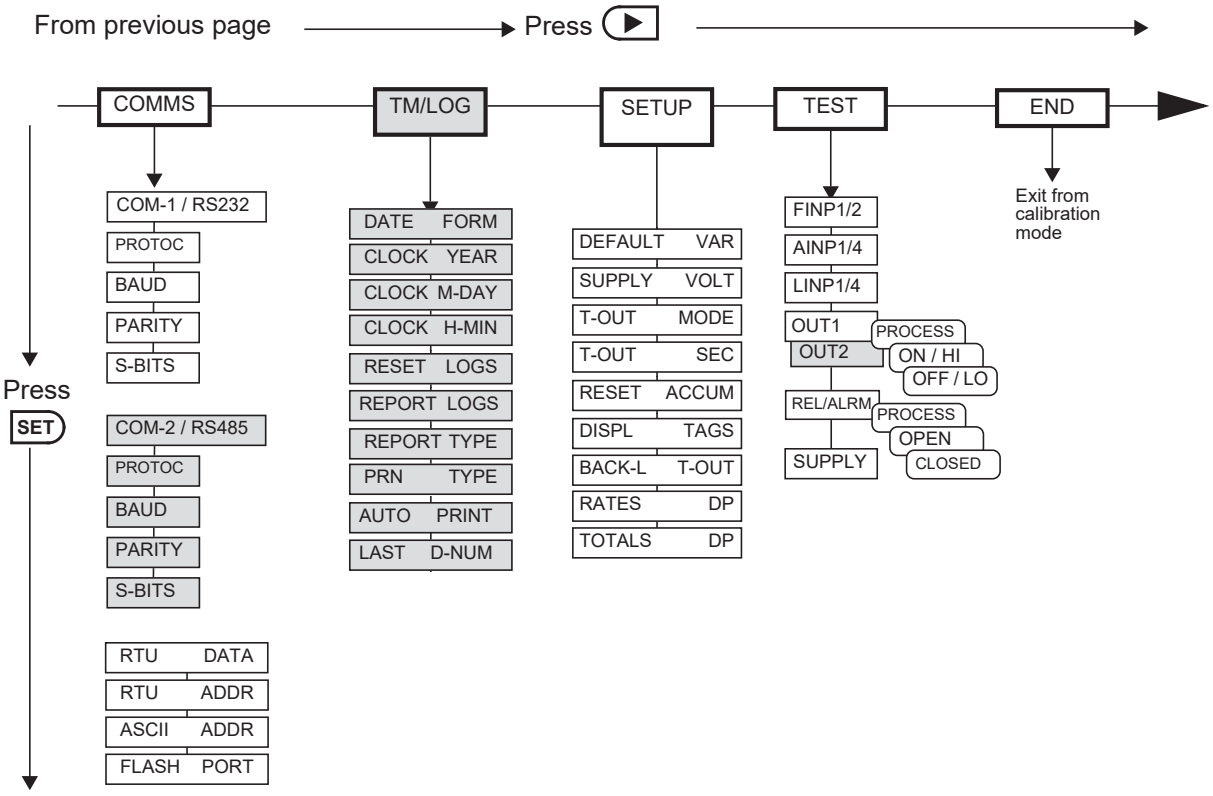


Figure 14 Calibration Menu Tree Sheet 1



The shaded boxes indicate hardware options

Hold DISPLAY at any point to return to the main calibration menu.

Press ▶ at any I/O assignment position to move to the next I/O assignment in the submenu (eg pressing ▶ on ALRM1 will move you to ALRM2 if it exists)

Figure 15 Calibration Menu Tree Sheet 2

Instrument Settings

Units of Measurement

The Units menu allows the units to be viewed and edited if necessary without the reloading of new application software. Any change in units will result in a full reset to initially downloaded settings. Therefore, any required changes to units of measurement should be made before changing any other settings.

SET ↓	▶ → **UNITS** PARAMS INPUTS OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
ITEM *n* *unit*	The units for main menu or calibration items can be viewed by pressing the SET key. The units of measurement are password protected. To edit the units the correct password must be entered on entry to EDIT mode. Press ▲ or ▼ to select the required units. Refer to **Available Units of Measurement** on page 84 for the list of available units.
ACCEPT UNITS	The Accept Units prompt will only appear if one or more of the units have been changed. **IMPORTANT:** Accepting the change of units will initiate a master reset. All calibration parameters will revert to their default value (i.e. those values included in the downloaded instrument software). All totals and any logged information will be cleared. Press ▲ or ▼ to select YES, then press the SET key. The instrument makes three beeps to confirm the reset command. The message -RESET- PLEASE WAIT will be displayed as the instrument exits calibration mode and completes a full re-boot sequence.

Parameters

SET ↓	▶ → UNITS **PARAMS** INPUTS OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
BATCH LIMIT	The batch limit determines the maximum batch preset value that can be entered. If a value of zero is entered for this parameter then no limit is applied. Enter the value in the engineering units of the batch preset.
P-STOP VALUE	The prestop value determines when relay 2 deactivates as the batch approaches the preset quantity. Enter the value in the engineering units of the batch preset.
ACCEPT TOTAL	The batch acceptable total is the minimum total for the system leakage to be logged (a value of zero disables logging of leakages). It also allows small totals due to “meter skips” and vibration to be discarded without being considered as a valid delivery. Enter the value in the engineering units of the batch preset.
S-STRT SEC	The batch slow start time determines when relay 2 activates after the start or resumption of a batch. Enter the value in seconds.
A-STRT SEC	The batch automatic restart time determines the time that will elapse between the end of one batch and the start of the next. A value of zero disables the auto restart feature. Enter the value in seconds.
T-OUT SEC	The batch flow timeout determines the length of no flow time that the instrument will wait during a batch before raising a no flow error. It also determines when an overflow error is raised if flow does not cease within the timeout period after the controller attempts to stop the flow. A value of zero disables these flow timeout features. Enter the value in seconds.
COUNT DIR	The batch count direction determines whether the batch total counts up from zero to the preset value or down from the preset to zero. Press ▲ or ▼ to select UP or DOWN.

SET ↓	▶ → UNITS **PARAMS** INPUTS OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
AUTO RESET	*This parameter is available for viewing and editing only when the batch automatic restart time is set to zero.* The automatic reset feature allows the previous batch total to be reset automatically when a new batch is started with the RUN key. Press ▲ or ▼ to select ENABLE or DISABLE.
AUTO COMP	The batch automatic overrun compensation allows the instrument to automatically compensate for any consistent overrun at the end of the batch. Overrun is typically due to the slowness of a valve to close or a pump to stop on receiving a signal from the batch controller and results in the delivered quantity being greater than the entered preset. In calculating the amount to be compensated for the instrument uses the average overrun from the last three batches. An overrun of more than 20% is considered invalid and will not be included in the calculations. Press ▲ or ▼ to select ENABLE or DISABLE.
STOP KEY	The function of the Stop key can be set to either Pause or Stop the delivery. Press ▲ or ▼ to select PAUSE or STOP.
No-SET BATCH	To provide faster access to commonly used preset values a number of batch presets can be preprogrammed into the instrument. This parameter allows the number of batch presets to be entered. Press ▲ or ▼ to select a number between 1 and 10.
SET-01 BATCH *to* SET-*n*	Enter the commonly used preset values for quick access via the front panel. Enter the value in the engineering units of the batch preset.
DIRECT ACCES	If the direct access is enabled then the operator is able to enter edit mode for the batch preset directly from the main menu by holding the SET key while viewing the preset. If disabled, the changes can only be made from within the calibration set mode (or via serial communications, see below). Select the direct access mode as required. Press ▲ or ▼ to select ENABLE or DISABLE.

SET ↓	▶ → UNITS **PARAMS** INPUTS OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
Modbus Accessible Parameters The following PARAMS menu items are also accessible via Modbus communications. For a complete Modbus parameter listing, refer to **Instrument Configuration Parameters** on page 73.	
PRESET BATCH	Enter the batch preset quantity. This setpoint is only available for PRESET batch mode. Enter the value in the engineering units of the assigned variable.
O-RUN COMP	Enter a fixed value batch overrun compensation that will allow the instrument to compensate for any consistent overrun at the end of the batch. Overrun is typically due to the slowness of a valve to close or a pump to stop on receiving a signal from the batch controller and results in the delivered quantity being greater than the entered preset. This value is only used for batch overrun compensation when auto overrun compensation is disabled. Enter the value in the engineering units of the assigned variable.

Inputs

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
Frequency Input 1	
INPUT TYPE	The flowrate and totalising calculations can be performed on either the frequency flow input or the analog flow input. • **FREQ** - frequency input using FINP1 • **ANALOG** - analog input using AINP3 Select the input type as required. Only relevant settings will be shown. Press ▲ or ▼ to select FREQ or ANALOG.
INPUT FLOW FINP1	For this application, the Frequency Input Channel 1 is assigned to mass flowrate.
SIGNAL FINP1	Frequency input 1 signal type. Press ▲ or ▼ to select COIL, NPS or PULSE.

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
DBNCE FINP1	Switches and relays have metal contacts to make and break circuits. The contact bounce introduces random signals into the circuit. The instrument has a debounce circuit to eliminate this problem. **Note:** When the debounce circuit is enabled, the maximum input frequency for large amplitude signals is limited to approximately 500 Hz. For low amplitude signals, the maximum frequency can be approximately 200 Hz. Press ▲ or ▼ to select ENABLE or DISABLE.
CUTOFF FINP1	The Cut-off is the lowest frequency for which the instrument continues to calculate a rate from the flowmeter. The value for the cut-off is specified as the frequency of the flowmeter in Hertz. Be careful when setting low cut-off values because the display update time for the flow rate becomes very long. For example if the cut-off is set to 0.01 Hz, and the measured flow stops, the instrument continues to display the flow rate for 100 seconds before it can determine that the flow has actually stopped.

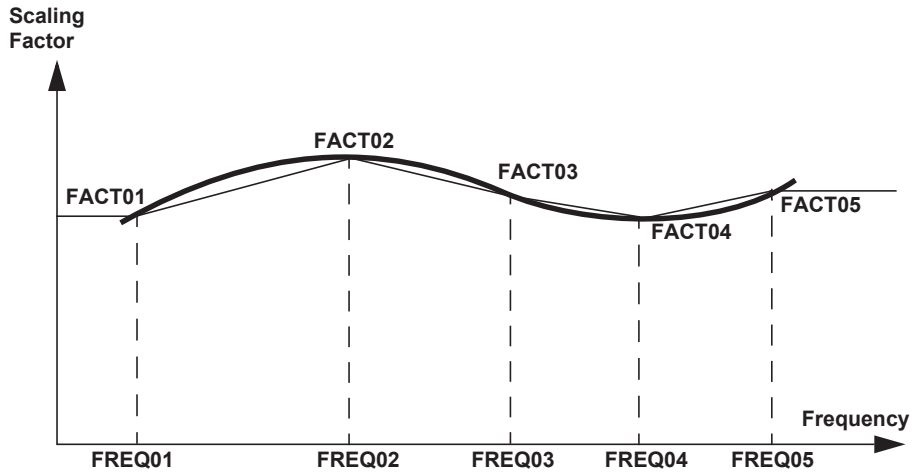
<table>
<tr><td>SET ↓</td><td>▶ → UNITS PARAMS INPUTS OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END</td></tr>
<tr><td>FILTER FINP1</td><td>Input fluctuations caused by pulsating flow tend to create distortion in the input readings of the rate. The instrument has a digital filter that averages out these fluctuations.

As a guide to the degree of filtering to use, the following table shows the response time (in seconds) to reach 90% and 99% of a step change in input.

The value A is the filter constant that the user can set.
<table>
<tr><th>Filter setting A</th><th>Seconds to reach 90% of full swing</th><th>Seconds to reach 99% of full swing</th></tr>
<tr><td>0</td><td>0</td><td>0</td></tr>
<tr><td>2</td><td>2</td><td>4</td></tr>
<tr><td>4</td><td>4</td><td>8</td></tr>
<tr><td>6</td><td>5</td><td>10</td></tr>
<tr><td>10</td><td>8</td><td>15</td></tr>
<tr><td>15</td><td>12</td><td>23</td></tr>
<tr><td>20</td><td>14</td><td>27</td></tr>
<tr><td>25</td><td>18</td><td>34</td></tr>
<tr><td>35</td><td>25</td><td>48</td></tr>
<tr><td>45</td><td>32</td><td>62</td></tr>
<tr><td>60</td><td>42</td><td>82</td></tr>
<tr><td>75</td><td>52</td><td>102</td></tr>
<tr><td>90</td><td>62</td><td>122</td></tr>
<tr><td>99</td><td>68</td><td>134</td></tr>
</table>
The input filter range is from 0 to 99. A setting of 0 (zero) means that there is no filtering.</td></tr>
<tr><td>CORR FINP1</td><td>If the input sensor has non-linear characteristics, select NON-LINEAR to apply correction factors to the input signal.

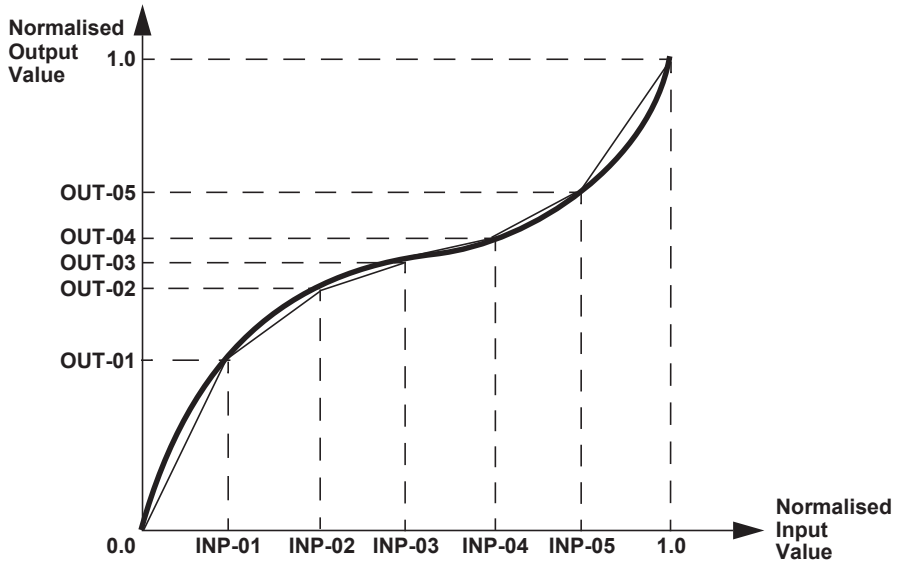
Use ▲ or ▼ to select LINEAR or NON-LINEAR.</td></tr>
<tr><td>KFACT1 unit</td><td>This parameter is available for viewing and editing only when the correction type is set to Linear.

The K-factor of the flowmeter is the number of pulses from the flowmeter per unit of volume (or mass). The K-factor cannot be 0 (zero).</td></tr>
</table>

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
NO-PTS FINP1	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the number of non-linearity correction points. Press ▲ or ▼ to select a number between 1 and 10 for the number of correction points.
FREQ01 FINP1 *to* FREQ*n*	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the frequency for this correction point. The instrument uses linear interpolation between the correction points except that the correction factor for FREQ01 is used from 0 Hz up to FREQ01. Similarly, the instrument maintains the correction factor for the highest frequency setting up to the maximum input frequency. The following diagram shows the scaling factors at different frequencies for a hypothetical flowmeter. The heavy black line represents the actual scaling factor of the flowmeter. The light black line is the approximation that the instrument uses.  Enter the lowest correction factor frequency as FREQ01 and proceed up to the highest frequency. You can press the DISPLAY key to skip the non-linear points and go to the next item.
FACT01 FINP1 *to* FACT*n*	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the scaling factor for this correction point in the same units of measure as the single K-factor above. The correction factor cannot be 0 (zero).

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
Analog Input 3	
INPUT FLOW AINP3	For this application, the Analog Input is assigned to mass flowrate.
TYPE AINP3	Select the type of analog input source. Press ▲ or ▼ to select 0-5V, 1-5V or 4-20mA.
PT-MIN AINP3 PT-MAX	Enter the value of the measured parameter (in the assigned engineering units) that corresponds to the minimum input signal level. The minimum point is commonly set at a base flowrate of 0.0. Enter the value of the measured parameter (in the assigned engineering units) that corresponds to the maximum input signal level. The maximum point is the same as the base value (set at the minimum point) plus the span value. For example, if the source signal is 4mA at a minimum mass flowrate of 0kg/M, enter 0 as the minimum point. If the source signal is 20mA at a maximum mass flowrate of 100kg/M, enter 100 as the maximum point.
CUTOFF AINP3	The Cut-off is the lowest value that the instrument reads from the input sensor. The cut-off setting is the percentage of the span of the input values. All inputs at or below the cut-off value are considered negligible to the instrument and are ignored. In this case, the instrument uses the minimum value (set at PT-MIN).
FILTER AINP3	Input fluctuations caused by pulsating flow tend to create distortion in the input readings of the rate. The instrument has a digital filter that averages out these fluctuations. As a guide to the degree of filtering to use, the following table shows the response time (in seconds) to reach 90% and 99% of a step change in input. The value A is the filter constant that the user can set.

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END		
	Filter setting A	Seconds to reach 90% of full swing	Seconds to reach 99% of full swing
	0	0	0
	2	2	4
	4	4	8
	6	5	10
	10	8	15
	15	12	23
	20	14	27
	25	18	34
	35	25	48
	45	32	62
	60	42	82
	75	52	102
	90	62	122
	99	68	134
	The input filter range is from 0 to 99. A setting of 0 (zero) means that there is no filtering.		
CORR AINP3	Analog input non-linearity can be corrected as follows: • LINEAR • SQUARE is used if the flowmeter requires square root extraction • NON-LINEAR to use the following linearity correction parameters Use ▲ or ▼ to select LINEAR, SQUARE or NON-LINEAR.		
NO-PTS AINP3	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the number of non-linearity correction points. Press ▲ or ▼ to select a number between 1 and 20 for the number of correction points.		

SET ↓	▶ → UNITS PARAMS **INPUTS** OUTPUTS ALARMS COMMS TM/LOG SETUP TEST END
INP-01 AINP3 *to* INP-*n*	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the normalised input value for the correction point. The instrument uses linear interpolation between the correction points. An input and an output value are entered for each correction point. The values are normalised between the minimum point (0.0) and the maximum point (1.0). Only the points between 0 and 1 are required to be entered and should be entered in ascending order. The following diagram shows a 5 point linearised representation of the input from a hypothetical transmitter. The heavy black line represents the actual input from the transmitter. The light black line is the approximation that the instrument uses.  You can press the DISPLAY key to skip the non-linear points and go to the next item.
OUT-01 AINP3 *to* OUT-*n*	*This parameter is available for viewing and editing only when the correction type is set to Non-linear.* Enter the normalised output value for the correction point.

Outputs

SET ↓	▶ → UNITS PARAMS INPUTS **OUTPUTS** ALARMS COMMS TM/LOG SETUP TEST END
FUNC OUT*n*	The output can function as either a pulse output for retransmission of totals, a no flow error signal, a pump control output or an end of batch signal. (Note: there is no End of batch signal if Batch mode is ON-OFF). Press ▲ or ▼ to select RETRANS, OP-ERR, OP-CTRL or OP-END
PULSE OUT*n* or 4-20	You can assign any of the "main menu" variables to an output. The nature of the output depends on the assigned variable. Totals are output as pulses and rates are output as 4-20 mA passive signals. Press ▲ or ▼ to select the variable that is required as an output. The top of the display shows the type of output signal that is assigned to the variable. **CAUTION** Due to the dual-purpose nature of the outputs, take care not to set the output as an open collector pulse type signal when connected to a 4-20 mA loop circuit.
WIDTH OUT*n*	*The Output Pulse Width is available for viewing and editing only when the assigned variable is a total (pulse output) type.* Pulse output is usually used to drive remote counters. Set the pulse width (in milliseconds) as required by the remote counter. Press ▲ or ▼ to set to: 10, 20, 50, 100, 200 or 500 ms.
PULSE OUT*n*	*The Output Pulse Factor is available for viewing and editing only when the assigned variable is a total (pulse output) type.* The Output Pulse Factor is the scaling factor for the retransmission of the measured total quantity. For example, if "volume" is chosen as an output variable and engineering unit is cubic metres, then a pulse factor of 1.000 generates one pulse for 1 m^3. Similarly, a pulse factor of 3.000 generates one pulse for 3 m^3. For more information, see **Output Pulse Factor** on page 47. The output pulse factor cannot be 0 (zero).

SET ↓	▶ → UNITS PARAMS INPUTS **OUTPUTS** ALARMS COMMS TM/LOG SETUP TEST END
PT-MIN OUTn PT-MAX OUTn	*The Output Minimum Point and Maximum Point are available for viewing and editing only when the assigned variable is a rate (4-20 mA output) type.* The output minimum value corresponds to the 4 mA point and the output maximum value corresponds to the 20 mA point. Setting the output range differently from the input range enables the instrument to amplify the input signal. You can drive a chart recorder that "zooms in" on a specified range of values instead of displaying the full operating range of the transducer. For example, if "volume flow" is chosen as an output variable and engineering unit is cubic metres per minute, then setting the minimum point to 30 and the maximum point to 100 would reflect the volumetric flow rate range of 30 to 100 m^3/min. At rates above the maximum and below the minimum points, the output remains at 20 mA and 4 mA respectively.

Output Pulse Factor

Increasing the output pulse width reduces the maximum frequency at which a total variable can be retransmitted. Pulses will be missed if the output cannot "keep up" with the rate of total counts. You can use the output pulse factor to ensure that this maximum is not reached.

The maximum pulse output frequency is determined by:

$$\frac{1000}{(2 \times \text{pulse width in ms})}\text{Hz}$$

The minimum pulse factor required is determined by:

$$\frac{\text{max rate of total}}{\text{max pulse output frequency}}$$

For example: To calculate the required pulse factor to avoid losing counts in retransmission if a total counts at a maximum rate of 75 units/sec (Hz) and the required pulse width of a remote counter is at least 50 ms:

The maximum pulse output frequency is: $\frac{1000}{2 \times 50} = 10\text{Hz}$

The minimum pulse factor for that frequency is: $\frac{75}{10} = 7.5$

Alarms

The alarm relay(s), in the advanced option, can be assigned to rate variables such as volume flowrate, or set as an equipment failure alarm.

The alarm switches “on” whenever an alarm condition exists. The alarm switches “off” when the alarm condition no longer exists. However, you may need to configure external alarm devices that require acknowledgement for cancelling an alarm.

Equipment Failure Alarm

Any alarm relay can be assigned as an equipment failure alarm. This alarm setting can have normally closed (open) contacts that open (close) when the instrument displays any error message as listed in **Error Messages** on page 56.

SET ↓	▶ → UNITS PARAMS INPUTS OUTPUTS **ALARMS** COMMS TM/LOG SETUP TEST END
RELAY ALRM*n*	Select a rate variable to assign to the alarm relay. **Note:** If the alarm type is set to “equipment alarm”, this relay assignment setting is ignored. Press ▲ or ▼ to select the variable that is required as an alarm.
TYPE ALRM*n*	The options available for alarm types are as follows: • HI-NO — High Alarm, Normally Open contacts • HI-NC — High Alarm, Normally Closed contacts • LO-NO — Low Alarm, Normally Open contacts • LO-NC — Low Alarm, Normally Closed contacts • BD-NO — Band Alarm, Normally Open contacts • BD-NC — Band Alarm, Normally Closed contacts • AL-NO — Equipment Alarm, Normally Open contacts • AL-NC — Equipment Alarm, Normally Closed contacts Press ▲ or ▼ to select the type of alarm required.
POINT ALRM*n*	*The Alarm Setpoint is available for viewing and editing for any alarm type except ‘equipment alarms’.* The Alarm Setpoint is the value (in engineering units of assigned variable) at which the alarm condition occurs and therefore the alarm is on. Each alarm is completely independent, e.g. a High alarm does NOT need to have a higher setpoint than the a Low alarm.

SET ↓	▶ → UNITS PARAMS INPUTS OUTPUTS **ALARMS** COMMS TM/LOG SETUP TEST END
HYST ALRM*n*	*The Alarm Hysteresis is available for viewing and editing for any alarm type except 'equipment alarms'.* Alarm hysteresis loops occur when the alarm toggles continuously on and off when the process variable is close to the setpoint. For a high alarm, the alarm activates when the value of the variable rises above the alarm setpoint and deactivates when the value falls below the alarm setpoint minus the amount of the hysteresis setting (if any). For a low alarm, the alarm activates when the value of the variable falls below the alarm setpoint and deactivates when the value rises above the alarm setpoint plus the amount of the hysteresis setting (if any). For a band alarm, the alarm activates whenever the value of the variable is outside the setpoint plus or minus the amount of the hysteresis. For example, with a high alarm setpoint of 200, and a hysteresis setting of zero, a value oscillating between 197 and 202 will cause the alarm to toggle on at 200 and toggle off below 200. However, if the hysteresis is set to 5, the value of the variable must fall below 195 to cancel the alarm. The alarm will reactivate only when the value again rises above 200.
DELAY ALRM*n*	The Alarm Delay is programmed in seconds and can be used to eliminate undesired alarm activation during start-up or shutdown operation.

Communications

The instrument has the following communication ports:

- **COM-1 RS-232 Port** - A 9-pin female connector on the rear panel of the instrument.
- **COM-2 RS-485 Port** (optional) - Terminals on the rear panel.
- **COM-3 Port**- A special communications port that is only applicable to some applications.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS **COMMS** TM/LOG SETUP TEST END
PROTOC COM-1 COM-2 COM-3	The Communications Protocols can be assigned to the communication ports as follows (a protocol cannot be assigned to more than one port at a time): • **ASCII** - Simple ASCII available for all ports • **RTU** - Modbus RTU available for all ports • **PRN** - Printer Protocol available for COM-1 and COM-2 • **NONE** - If a port is not being used, set the protocol to NONE. Printer Protocol (PRN) is only available if the option with Real Time Clock is installed. For the selected port, press ▲ or ▼ to select the desired protocol.
BAUD COM-1 COM-2 COM-3	The Baud setting is the speed of the communication port in data bits per second. The baud rate of the instrument must match the baud rate of the communication device that the instrument is connected to. Use ▲ or ▼ to select 2400, 4800, 9600 or 19200 baud.
PARITY COM-1 COM-2 COM-3	The Parity bit helps to detect data corruption that might occur during transmission. The parity bit setting of the instrument must match the parity bit setting of the communication device that the instrument is connected to. Press ▲ or ▼ to select EVEN, ODD, or NONE.
S-BITS COM-1 COM-2 COM-3	The Stop bit indicates the end of a transmission. Stop bits can be 1 or 2 bit periods in length. The stop bit setting of the instrument must match the stop bit setting of the communication device that the instrument is connected to. Press ▲ or ▼ to select 1 or 2 stop bits.
RTU DATA	The Modbus RTU data format for the 2-register (4-byte) values can be set as either floating point or long integer values. Use ▲ or ▼ to select FLOAT or INTEGER.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS **COMMS** TM/LOG SETUP TEST END
RTU ADDR	The Modbus RTU protocol address must be in the range of 1 to 247. When multiple instruments (slaves) are connected to one communication device (master), each assigned address must be unique. **Note:** The master device uses the RTU address 0 (zero) for broadcasting to all connected slave units.
ASCII ADDR	The ASCII protocol address identifies each communicating device. The address must be in the range of 1 to 255. When multiple instruments (slaves) are connected to one computer (master), each assigned address must be unique.
FLASH PORT	The Flash Driver Port assignment defines the communication port for downloading software into the instrument. The default setting of this assignment is the RS-232 port. Press ▲ or ▼ to select RS-232, RS-485, or INFRA.

Time Settings and Data Logging

Instrument Clock

Note: The real-time clock is part of the advanced option package.

The instrument has a real-time clock for recording logged events. The clock displays the time and the date. The date format can be set to European format (day/month/year) or American format (month/day/year). The time clock uses the 24-hour format.

The clock will continue to operate for up to 5 years (typically) on the internal battery if there is no power connected to the instrument. Therefore, after an interruption to the power supply, the instrument recommences normal operation although there will be no data recorded during the period without a power supply.

Note: If there is an interruption to the power supply and the battery has failed, the instrument displays an error message when the power supply is restored. In this case, you should set the current time and date so that the instrument continues to log data at the correct times.

Data Logging

The instrument will log a total of 1000 deliveries (batches) if the real-time clock option is installed. The logs are taken at the end of each batch or upon reset if a batch has been aborted before the preset total has been reached.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS COMMS **TM/LOG** SETUP TEST END
DATE FORM	Clock Date Format The European date format is: dd/mm/yyyy or (Day-Month). The American date format is: mm/dd/yyyy or (Month-Day). Press ▲ or ▼ to select DAY-M or M-DAY
CLOCK YEAR	The Clock Year defines the current year for the real-time clock.
CLOCK M-DAY	The Clock M-DAY setting defines the current month and date for the real-time clock. This parameter is programmed in Month-Day format for both European and American date formats.
CLOCK H-MIN	The Clock H-MIN setting is the current time in hours and minutes for the real-time clock.
RESET LOGS	Reset the logged data. You may need to reset (clear) the logged data if you change the time/log settings. Press ▲ or ▼ to select YES, then press the SET key. The instrument makes three beeps to confirm the reset command.
REPORT LOGS	The Printer Protocol Report Logs defines the number of latest logs to be included into a printable report. Enter the number of logs between 0 and 99.
REPORT TYPE	The Printer Protocol Report Type determines the nature of the printout from the REPORT PRINT - HOLD.SET prompt in the main menu. The following report types available in this instrument are: • REP-10 Preset number of latest logs Press ▲ or ▼ to select Report Type.
PRN TYPE	The Printer Protocol Printer Type allows the nature of the printer being used to be specified. The following printer types available in this instrument are: • PRN-01 Generic computer printer • PRN-02 Generic roll printer (prints first line first) • PRN-03 Slip printer TM295 • PRN-04 Label (roll) printer - Citizen CMP30L Press ▲ or ▼ to select Printer Type.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS COMMS **TM/LOG** SETUP TEST END
AUTO PRINT	The Auto Print function, if enabled, allows a delivery docket print out to occur automatically at the End of Batch. If disabled, a printout must be initiated via the HOLD.SET - TO PRINT prompt in the main menu. Press ▲ or ▼ to select ENABLE or DISABLE.
LAST D-NUM	This defines the "last delivery number", so the delivery number counting continues from this value. Note: this parameter is accessible only when Logging is reset (either explicitly or when application is loaded into unit). Enter the required delivery number.

General Setup Parameters

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS COMMS TM/LOG **SETUP** TEST END
DEFAULT VAR	Select the main menu variable to display on power up or when the display timeout period has elapsed if it is enabled. Press ▲ or ▼ to select the default variable display.
SUPPLY VOLT	The instrument provides a power-limited supply for external transducers. Press ▲ or ▼ to set the transducer supply voltage between 8 and 24 volts DC as required.
T-OUT MODE	If the Display Timeout mode is enabled, and there is no user activity for the defined timeout period, the display panel returns to the default display. This function is useful for the following reasons: • to return the display to a preferred variable after the user has finished reading other information, • to cancel the calibration mode and return to the default display if the user does not exit from the calibration mode for any reason. Press ▲ or ▼ to select the display timeout function as follows: • **DISABLE** - Timeout is completely disabled. • **EN DISP** - Timeout is enabled during Normal mode and Calibration View mode. • **EN EDIT** - Timeout is enabled during Calibration Set mode. • **EN ALL** - Timeout is enabled for all modes.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS COMMS TM/LOG **SETUP** TEST END
T-OUT SEC	The Display Timeout period defines the delay for the Display Timeout mode if it is enabled. The display timeout period can be from 10 to 99 seconds.
RESET ACCUM	The Reset Accumulated Totals function clears all of the accumulated totals and the non-accumulated totals. Press ▲ or ▼ to select YES, then press the SET key. The instrument makes three beeps to confirm the reset command.
DISPL TAGS	The Display Tags option determines whether the instrument displays the default display tags or the user-defined tags. The display tag setting also defines whether the instrument displays the default error and warning messages, or the user-defined messages. **Note:** The user-defined tags can be entered into the instrument only by the manufacturer or the distributor. Press ▲ or ▼ to select the Display Tags option as follows: • **DEFAULT** - the instrument displays the default (English) tags • **USER** - the instrument displays the user-defined tags.
BACK-L T-OUT	If the backlight timeout is enabled, and there is no user activity (any keys pressed) for a period of 10 seconds, the display backlight switches off to save power. The backlight switches on when a key is pressed. Select the backlight timeout mode as required. Press ▲ or ▼ to select ENABLE or DISABLE.
RATES DP	This parameter sets the maximum number of decimal places for displaying or printing main menu rates.
TOTALS DP	This parameter sets the maximum number of decimal places for displaying or printing main menu totals.

Test Menu

The Test menu enables you to view the inputs and outputs to and from the instrument.

In Calibration Set mode, (by entering the system password) you can control the outputs and the alarms as described in the table below.

SET ↓	▶ → UNITS PARAMS INPUTS OUPUTS ALARMS COMMS TM/LOG SETUP **TEST** END
FINP*n* Hz	The frequency of the input to FINP*n* is displayed in Hertz.
AINP*n* *units*	The units are displayed according to the calibration setup for the analog input. If unused or set to Default the input is 4-20mA and displayed in mA.
LINP*n* STATE	You can view the state of the logic inputs. If the input is an open contact or inactive it will display **HI**. If the input is a closed contact or active it will display **LO**.
OUT*n* STATE	You can control the state of the outputs. Press the ▲ or ▼ keys to set the output state as follows: • **PROCESS** - the output depends on the current values of the inputs and the calculations that the instrument performs. For a pulse output, such as a total, the output produces a pulse train as follows: • **ON** - a pulse train with a pulse width as set for the particular output in the Outputs menu. • **OFF** - no output. For a 4-20mA output, such as a rate, the output is as follows: • **HI** - the output is set to 20mA. • **LO** - the output is set to 4mA.
ALRM*n* STATE *or* REL-*n*	You can control the state of the relays (alarms). Press the ▲ or ▼ keys to set the selected relay as follows: • **PROCESS** - the relay operates according to the current values of the inputs and the relay settings as programmed. • **OPEN** - the relay output contacts are set to “open”. • **CLOSED** - the relay output contacts are set to “closed”.
SUPPLY V	You can display the actual DC output supply voltage, which may help with troubleshooting. If the actual supply voltage is lower than the preset value (refer to **General Setup Parameters** on page 53) it may indicate that the output is overloaded.

System Messages

The instrument displays messages for defined events and fault conditions.

The manufacturer or distributor can enter user-defined text for the messages. This user-defined text is displayed, instead of the default (English) messages, when the Display Tags option in the Setup menu is set to USER.

Error Messages

The system displays error messages, and records the associated exception status code, in the order of highest to lowest priority as listed in the following table:

Error Messages	**Status Code**	**Description -** (Highest Priority at top of table).
CPU Card Failure	20	There are failed components on the CPU card and technical support is required.
Power Supply is Low	21	The input and/or output power supply voltage is too low, ensure that: (a) input power supply voltage is within the specified range (b) output power supply is not overloaded.
New/Failed Battery - Set Time	22	The real-time clock has lost the correct time because the battery has failed, or there is a new battery. Set the current time and date (in the TM/LOG menu) to clear the error message and to continue data logging at the correct times. **Note:** The instrument can continue operating with a failed battery, but the correct time will be lost if there are interruptions to the power supply.
Analog Input 3 Signal Failure	03	The analog flowrate transmitter has failed (analog input 3). It is not possible to override this error condition. The instrument cannot operate without a flowrate input.
No Flow Detected	12	The no flow condition is detected when the flow timeout expires during a delivery. There must not be a period of no flow greater than the timeout value during the delivery.
Unexpected/ Over Flow	13	The unexpected/over flow condition is detected when the flow continues longer than the timeout period after the controller has attempted to stop (or pause) the flow.
Leakage Detected	14	The leakage condition is detected when an amount greater than the acceptable total is received without flow being initiated by the batch controller.

Warning Messages

The system displays warning messages as described in the following table:

Warning Messages	Description
Value Has Been Set to Default	You have entered an invalid value for a parameter. Therefore, the instrument has set the default value.
Already Assigned to Other Port	You have tried to assign a particular protocol type to more than one serial communication port. The instrument has set the protocol to NONE.
Preset Over Limit - Max Set	You have exceeded the preset limit. The instrument will set the maximum allowed value.

Chapter 6
Communications

Overview

This chapter describes the communications between the instrument and another communicating device such as a computer or a printer. You should have relevant information about the devices to which the instrument will be connected. Some connection examples are included in this manual, however, the operation and connection of other devices is outside the scope of this manual.

Hardware Interconnection

The instrument has two communication ports:

- COM-1 RS-232 port on the rear panel (DB9 female connector)
- COM-2 RS-485 port on the rear panel (optional)

The appropriate interface and protocols are selected during calibration.

COM-1 RS-232 Port

The COM-1 RS-232 port provides communication between the instrument and one other device such as a host computer or a printer.

Note: A printer must have a serial port to be able to be directly connected to the flow computer. It is not possible to communicate directly with a printer via a parallel port.

Computers use either a DB9 or a DB25 connector, and the connections to each type are shown in Figure 16.

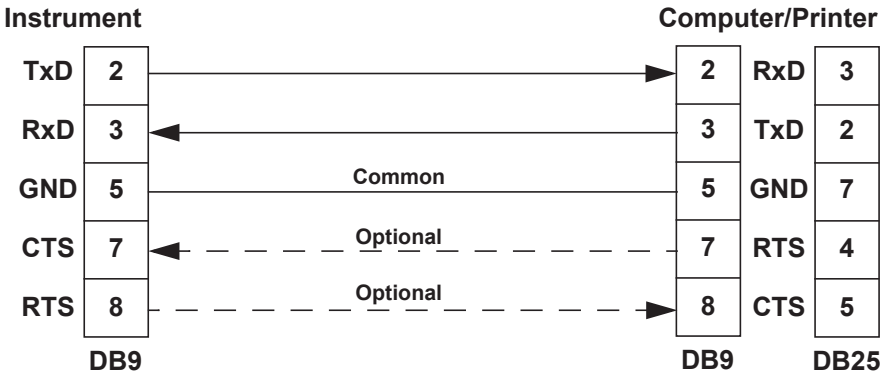


Figure 16 RS-232 Cable Connections to a Computer

Note: The instrument requires a cable with straight-through connections. Do not use a null modem cable for RS-232 connection to a computer.

COM-2 RS-485 Port

The COM-2 RS-485 port enables communication with multiple devices. Each device has a unique address so that the "master" device can communicate with specific "slave" devices.

On RS-485 links, an external terminating resistor must be connected at the furthest end of the cable. When multiple instruments are connected, they should be "daisy chained" in a multidrop configuration as shown in Figure 17. Up to 32 units can be connected to the interface at a maximum distance of 1200 metres.

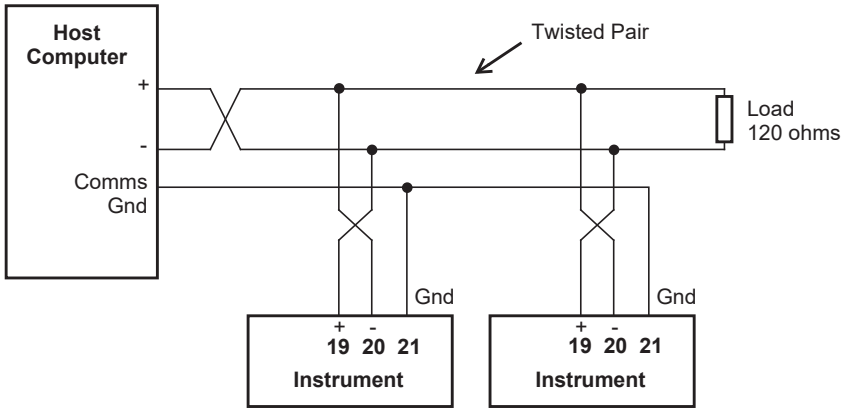


Figure 17 RS-485 Connections

Protocols

The communications protocols can be assigned to the communication ports on the instrument as follows:

- **ASCII** - Simple ASCII available for all ports
- **RTU** - Modbus RTU available for all ports
- **PRN** - Printer Protocol available for COM-1 and COM-2
- **NONE** - If a port is not being used, set the protocol to NONE.

Note: The Printer Protocol is only available if the option with Real Time Clock is installed. Also a protocol cannot be assigned to more than one port at a time as described in **Communications** on page 49.

- **ASCII** - In this ASCII protocol each command and response is a string of ASCII characters. This proprietary protocol is developed by Contrec to allow for simple information interchange. The main advantages of this mode are that it allows extended time intervals to occur between characters without causing a timeout error and that messages can be sent and monitored easily with a simple ASCII terminal.
- **Modbus RTU** - Modbus RTU is an industry-standard protocol which allows the instrument to be easily connected to computers running supervisory software systems. The main advantage of this mode is that its greater character density allows better data throughput than ASCII mode, however each message must be transmitted in a continuous stream.
- **Printer** - In the Printer protocol there is a selection of printer types. Please refer to the **Printer Protocol** on page 74 for full details.

Simple ASCII Protocol

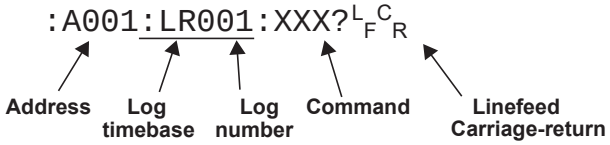
Note: Not all ASCII commands are applicable for Batch Controller applications.

This simple ASCII protocol requires that all requests are initiated with a colon (:) and terminated with a carriage return ($^{C}_{R}$). The message termination can include a linefeed before the carriage-return ($^{L}_{F}{}^{C}_{R}$), but it is the carriage-return that acts as the message termination.

All responses by the instrument are terminated with a linefeed and a carriage-return ($^{L}_{F}{}^{C}_{R}$).

Requests Format

The format of a request to the instrument is as follows:



Each request must include the address and command portions. The underlined section is an optional part of the request string.

Address

In multipoint communications, each instrument must have a unique address and it is essential in the request for identifying a particular instrument. However, it may be set to 000, for special broadcast commands. For single-instrument communications, the address can also be set to 000 in the request.

Refer to **Communications** on page 49 for setting the instrument address.

Note: The instrument always responds with its address in the header regardless of the type of request.

Log Type and Number

The log type and number enables a communicating device to retrieve data from the instrument. The data can be from the event-based logs or from the current process variables with the either accumulated or non-accumulated (resettable) totals.

The log request is optional. If the log request is not included, or the log number is set to 000, the instrument returns the current process variables. If the log request is included, the log number defines the specific log entry by counting backwards. The most recent log entry for a timebase is 001.

The “last edit” log records the process variables at the time of the last exit from the calibration edit mode. There is only one “last edit” log, therefore, if a number is included in the request, the instrument ignores the number and returns the data at the time of the last edit. Likewise, there is only one set of current process variables with “non-accumulated totals”, therefore it also ignores any log number included in that request.

The types of the logs applicable to this instrument are as follows:

Log Type
LE - last edit log
LR - logged records (non-timebased logging)
LN - current totals displayed as Non-accumulated

The number of the log entry is the same as shown on the front panel of the instrument. For example, a request for LR003 would return the data for the log entry two batches prior to the most recent batch log entry.

Instrument Responses

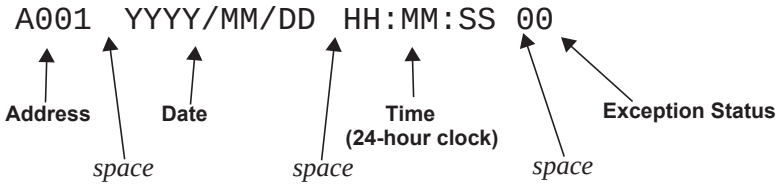
The instrument response time to any enquiry is not more than 300 ms. The responses from the instrument are in the following format:

HEADER$^{L}_{F}{}^{C}_{R}$
DATA$^{L}_{F}{}^{C}_{R}$
DATA$^{L}_{F}{}^{C}_{R}$
.
.
.
DATA$^{L}_{F}{}^{C}_{R}$
$^{L}_{F}{}^{C}_{R}$

The components of the response message are as follows:

Header

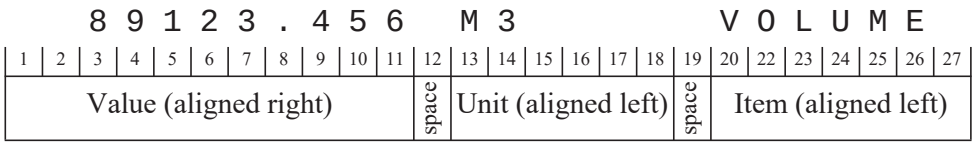
The format of the response header from the instrument is as follows:



The instrument **Exception Status** codes that the instrument returns for the ASCII protocol are the same as those described for the Modbus RTU protocol in **Instrument Exception Status** on page 70.

Data

The format of the data variables from the instrument is as follows:



Note: The decimal point in the Value is always at character position 8. Therefore whole numbers are aligned right at the decimal point, with trailing zeroes.

Variables Request

The variables request asks the instrument to return the value of one or more requested variables. All totals are transmitted as accumulated totals.

Command	Description
:RVA?	Return all variables
:RVD?	Return the default Total and Rate
:RV0? … :RV9?	Return the specific variable. The numbers relate to the position in the variables menu. For example, V0 is Energy, V1 is Power and so on.

Variables Request and Response Example

The following request is for the only instrument that is connected to the communication port to return the values of all main menu variables.

```
:A001:RVA?LF CR
```

The following is an example of a hypothetical instrument response. Refer to on page 3 for the list of variables that would be returned for this application.

```
A001  2002/03/14  18:25:00  00LF CR
        6.116  MWh       ENERGY  LF CR
       16.573  MW        POWER   LF CR
    1320.530  m3        VOLUME  LF CR
       58.300  m3/M      V-FLOW  LF CR
    7627.117  KG        MASS    LF CR
      344.460  KG/M      M-FLOW  LF CR
      230.000  DEG  C    TEMP    LF CR
        1.260  MPA       PRESS   LF CR
        0.174  m3/KG     SP-VOL  LF CR
    2886.760  KJ/KG     SP-ENT  LF CR
LF CR
```

The following message to an instrument, requests the current values for the default rate and total:

```
:A001:RVD?LF CR
```

The instrument response would be similar to the following:

```
A 0 0 1   2 0 0 2 / 0 3 / 1 4   1 8 : 2 5 : 0 0   0 0 LF CR
      1 2 6 . 4 5 5   m 3         V O L U M E   LF CR
        2 0 . 4 3 7   m 3 / M     V - F L O W   LF CR
LF CR
```

Log Request

The log request asks the instrument how many logs will be included in a printed log report. These are the values described in **Time Settings and Data Logging** on page 51.

Command	Description
:RLR?	Return the number of log records (non- timebased logging)

Log Response Example

The following message asks the instrument with address 001 to return the number of logs that the instrument stores:

```
: A 0 0 1 : R L R ? LF CR
```

The instrument response would be similar to the following:

```
A 0 0 1   2 0 0 2 / 0 3 / 1 4   1 8 : 2 5 : 0 0   0 0 LF CR
2 4 LF CR
LF CR
```

Clear Data Request

The clear data request asks the instrument to clear the data in the selected registers.

Command	Description
:RCN?	Clear the non-accumulated (resettable) totals
:RCA?	Clear the accumulated totals
:RCL?	Clear the logs except for the “last edited” log

Clear Data Request Example

The following message asks the instrument with address 001 to clear the logged data that the instrument stores:

```
: A 0 0 1 : R C L ? LF CR
```

The instrument response would be similar to the following:

```
A 0 0 1   2 0 0 2 / 0 3 / 1 4   1 8 : 2 5 : 0 0   0 0 LF CR
LF CR
```

Instrument Information Request

The Instrument Information request asks the instrument to return the general information about the model and version codes. The instrument exception status is returned as a part of the header as it is with the header for all command responses.

Command	Description
:RIG?	Return the general information about the instrument such as Model number, Application number, Version and Serial numbers etc. These items are returned as a block in the same format as shown on the display in the “Model Info” menu.

Instrument Information Response Example

The following message asks the instrument with address 001 to return the general information about the instrument:

```
: A 0 0 1 : R I G ? LF CR
```

The following is an example of a hypothetical instrument response:

```
A 0 0 1   2 0 0 2 / 0 3 / 1 4   1 8 : 2 5 : 0 0   0 0 LF CR
5 1 5       M O D E L     - 1 1 - F - LF CR
S C 0 1     I N P U T     F - T P - - LF CR
S C 0 1     V E R S     0 1 0 1 . 0 0 1 LF CR
C U S T O M  V E R S      0 0 0 0 0 1 LF CR
U N I T     S / N         1 2 3 4 5 6 LF CR
LF CR
|1|2|3|4|5|6|7|8|9|10|11|12|13|14|15|16|17|18|19|20|21|22|23|24|25|26|27|28|29|
```

Corrupted or Invalid Requests

If the instrument receives a corrupted or incomplete request, there is no response. The instrument discards any partial request and waits for the next enquiry.

If the instrument receives a request message in the correct format, but for a non-existent option, it returns only the message header. For example, if the instrument received the following request variables message :A001:RVT? it will return only the header because there is no T option for the ‘Variables Request’ message.

Modbus RTU Protocol

Modbus RTU (remote terminal unit) is an industry standard protocol that allows the instrument to be easily interfaced to other communication devices.

The instrument implements the Modbus protocol as detailed in the *Modicon Modbus Protocol Reference Guide* PI-MBUS-300 Rev J (June 1996).

Message Format

In RTU mode, messages start with a silent interval of at least 3.5 character times. The first field transmitted is the device address. Following the last transmitted character, a similar interval of at least 3.5 character times marks the end of the message. A new message can begin after this interval. The entire message frame must be transmitted as a continuous stream. A typical message frame is shown below:

Address	Function	Data	CRC Check
1 byte	1 byte	n bytes	2 bytes

Except for broadcast messages, when a master device sends a query to a slave device, it expects a normal response. One of four possible events can occur from the master's query:

- If the slave device receives the query without a communication error, and can handle the query normally, it returns a normal response.
- If the slave does not receive the query due to a communication error, no response is returned. The master program has to process a timeout condition for the query.
- If the slave receives the query, but detects a communications error (parity or CRC), no response is returned. The master program has to process a timeout condition for the query.
- If the slave receives the query without a communication error, but cannot handle it (for example, if the request is to read a nonexistent register), the slave will return an exception response informing the master of the nature of the error.

Instrument Address

The address of the instrument is programmable in the range from 1 to 247. Some addresses are reserved according to PI-MBUS-300 and have a special meaning:

- 0 = Broadcast, no response required from slave devices
- 248 to 255 Reserved

Function Codes

The instrument accepts the following function codes:

Code	Name	Description
03	Read data register(s)	Obtain the content of one or more 2-byte data registers.
06	Preset data register	Preset one 2-byte data register.
07	Read status register	Obtain the content of 1-byte status register.
16	Preset data register(s)	Preset one or more 2-byte data registers.

Exception Response

The instrument forms an exception response by adding 80H to the function code and using an exception code as the 1-byte data field in the returned frame. Implemented exception codes are as follows:

Code	Name	Description
01	Illegal function	The function code is not a legal action for the slave.
02	Illegal data address	The data address is not a legal address for the slave.
03	Illegal data value	The data value is not a legal value for the slave.
05	Acknowledge	The slave has accepted the request and is processing it, but a long duration of time will be required to do so.
06	Slave device busy	The slave is engaged in processing a long duration program command. The master should re-transmit the message later when the slave is free.

List of Data Registers

The following list describes the addresses and meaning of the data registers in the instrument. The data values are expressed in the engineering units that were selected for the variables when the instrument settings were configured. The “Data Type” for the 2-register (4-byte) data values can be set in programming mode as Floating Point or Long Integer as described in **Communications** on page 49.

The registers are grouped in blocks that relate to a particular function of the instrument.

Note: Conventional numbering of registers often starts from 1, therefore be aware that “register 1” in this case has “address 0” and so on.

Current and Logged Process Data

This block of registers is available for the retrieval of current or logged process data with its matching time and date information.

Use the log timebase and log number to retrieve the logged information from the appropriate register. If a particular log number does not exist, or the instrument does not have the optional real-time clock, the time and date stamp and associated variables are set to zero.

Register	Name	Comments	Read Only or Read/Write	Type
1	Mass	Process Variables By default totals are the Accumulated values. If current Non-accumulated (resettable) totals are required, set register 37 to 06.	R	DT*
3	Mass Flowrate		R	DT
5			R	DT
7			R	DT
9			R	DT
11			R	DT
13			R	DT
15			R	DT
17			R	DT
19			R	DT
21			R	DT
23			R	DT
25			R	DT
27			R	DT
29			R	DT
31	Year	Current Date/Time or Logged Date/Time Stamp (see register 38 Log Number). Only current Date/Time can be edited	R/W	I†
32	Month		R/W	I
33	Date		R/W	I
34	Hour		R/W	I
35	Minute		R/W	I
36	Second		R	I
37	Log Type	00 - hourly or log records 01 - daily 02 - weekly 03 - monthly 04 - yearly 05 - last edit of calibration 06 -current totals are non-accumulated values, register 38 is ignored.	R/W	I
38	Log Number	If set to 0, current variables and Date/Time are retrieved	R/W	I
39	Clear Data	01 - clear logs 02 - clear accumulated totals 03 - clear non-accumulated totals	W	I
40	Reserved			

* DT = Data Type of 2-register (4 byte) values can be set as Floating Point or Long Integer values

† I = Integer (2 bytes) (Holding Registers)

Note: The Floating Point variable is represented in IEEE-754 Floating Point 4-byte format and requires two 2-byte data registers:

IEEE-754	Modicon Registers
1st byte	low byte (register X)
2nd byte	high byte (register X)
3rd byte	low byte (register X+1)
4th byte	high byte (register X+1)

This means that two data registers must be read or written to obtain, or preset, one data value.

Instrument Exception Status

This register is available to verify the status of the instrument.

Register	Name	Comments	Read Only or Read/Write	Type
41	Exception Status	00 = no error 01 = analog input 1 failure 02 = analog input 2 failure 03 = analog input 3 failure 04 = analog input 4 failure 05 = invalid calibration parameter 06 = invalid reference parameter 07 = invalid property 08 = quadrature input error 09 = quadrature input frequency over limit 10 = process parameters out of range 11 = input is over limit 12 = no flow error detected 13 = overflow error detected 14 = leakage error detected 20 = system failure 21 = power supply is low 22 = new or failed clock battery 23 to 29 reserved 30 = alarm 1 active 31 = alarm 2 active 32 = alarm 3 active 33 = alarm 4 active	R	I*

* I = Integer (2 bytes) (Holding Registers)

Instrument Control and I/O

This block of registers is available in some applications to give access to important information in the instrument.

Register	Name	Comments	Read Only or Read/Write	Type
42	Reserved		R	I*
43	Logic Inputs	0 to 15 Binary representation of logic inputs B0 = 0/1 (LSB) input 1 activated/deactivated B1 = 0/1 input 2 activated/deactivated B2 = 0/1 input 3 activated/deactivated B3 = 0/1 input 4 activated/deactivated	R	I
44	Operation State	Representation of operation status 0 = Reset 1 = Maintenance 2 = Completed 3 = Waiting to restart 4 = Paused 5 = Waiting for timeout 6 = Running (Slow Start) 7 = Running (Prestop) 8 = Running (Full Flow)	R	I
45	Relay State	0 to 15 Binary representation of relay state. 0 = open; 1 = closed. B0 = relay 1 (LSB) B1 = relay 2 B2 = relay 3 B3 = relay 4	R	I
46	Relay Control	0 to 15 Binary representation of relay control. 0 = open; 1 = close. **Note:** Only the general relays configurable in the Alarm section of calibration are able to be viewed and controlled by Modbus. B0 = relay 1 (LSB) B1 = relay 2 B2 = relay 3 B3 = relay 4	R/W	I
47	Relay Control Source	0 to 15 Binary representation of relay control source. 0 = Local (controlled by instrument operation) 1 = RTU (controlled by Modbus register 46). B0 = relay 1 (LSB) B1 = relay 2 B2 = relay 3 B3 = relay 4	R/W	I
48	Delivery Number	Provides the delivery number (batch record) for a stored transaction (determined by Modbus register 38).	R	L†
50	Control Mode	0 = Idle/Local Control from logic inputs 1 = Stop Suspend current batch 2 = Run Resume/start batch 3 = Reset Clear current batch totals	R/W	I
51 to 99	Instrument Parameters	See next table for details.	R/W	DT‡

Register	Name	Comments	Read Only or Read/Write	Type
101	Analog Inp.1	Raw analog input data. 4-20mA inputs are read in Amperes. 0-5V or 1-5V inputs are read in Volts RTD inputs are read in degrees Kelvin. Unused inputs are configured as 4-20mA.	R	DT
103	Analog Inp.2		R	DT
105	Analog Inp.3		R	DT
107	Analog Inp.4		R	DT

* I = Integer (2 bytes) (Holding Registers)

† L = Long Integer (2 register = 4 bytes)

‡ DT = Data Type of 2-register (4 byte) values can be set as Floating Point or Long Integer values

Instrument Configuration Parameters

This block of registers is available in applications to give access to some important instrument parameters (i.e. fluid properties etc.).

The usage of these parameters can be dependent on other instrument settings. For full description, please refer to the **Modbus Accessible Parameters** on page 39.

Register	Name	Comments	Read Only or Read/Write	Type
51	Batch Preset Value		R/W	DT
53 to 99	Reserved		R/W	DT

Printer Protocol

A printer protocol is available in the 500 Series. It provides the ability to print out live data, individual logged data and to do some report-style printing of logged data. The method of printing these and the format of the printouts is described below.

Note: Printer output is only available if the Real Time Clock option is fitted.

The selection of Printer Protocol can be made for the Communications Protocol options for the RS232 or RS485 port. A list of log report types and printer types available at the end of the TM-LOG calibration menu.

Report Types

The list of report types is as follows:

- REP-10 Latest Logs Report

The number of logs printed in each report are determined by the values programmed for Report Logs in the TM-LOG menu.

Printer Types

The list of available printers is as follows:

- PRN-01 Generic computer printer
- PRN-02 Generic roll printer (printing first line first)
- PRN-03 Slip Printer TM295
- PRN-04 Label (roll) printer - Citizen CMP30L

Customizing a Printout

A customized printout can be provided which can have up to 4 header lines and 3 footer lines. It is also possible to include or exclude each main menu items on the printout. If any customizing of the printout is required discuss this with the distributor.

Types of Printouts

Live Data

The HOLD.SET - TO PRINT prompt in the main menu, is used to initiate a printout of the current delivery if the printer protocol has been selected. A printout can only be initiated if a batch is not in progress. If printing is not required, do not select printer protocol.

The format of this printout will be:

Custom Header Lines

Instrument Serial No. & Tag

Current Delivery No.
Current Date & Time & Status
Variable unit value
Variable unit value
etc.

Custom Footer Lines
---------- *<separation line>*

(Note that blank header and footer lines are not printed).

Instrument Serial Number and Unit Tag

The instrument serial number and unit tag is the same as the information shown in the Model Info menu. For more details refer to **Model Information** on page 24

Delivery Number

The delivery number that appears on the live data printout shows the assigned delivery number that is stored with the logged data. This number is cleared when the Logs are cleared in the TM/LOG menu. If a second print or docket of the same delivery is generated, the words “(DUPLICATE DOCKET)” are included at the top of the printout. i.e.

(DUPLICATE DOCKET)

####

DELIVERY No. 000256

Individual Log Data

When in the Log Menu and while holding the DISPLAY key to view the data of the log of interest, the RESET key can be pressed to initiate a printout of that log entry. The printout will have the time and date stamp corresponding to when the log was taken. After the print has been initiated there will be the opportunity to scroll to view another log entry and print again.

Since each log entry stores the delivery totals only, the printout will not have any accumulated totals. The format of the printout with this exception is the same as the LIVE DATA printout:

Custom Header Lines

Instrument Serial No. & Tag

Logged Delivery No. *number*
Date & Time & Status
Variable *unit* *value*
Variable *unit* *value*
etc.

Custom Footer Lines
---------- *<separation line>*

Log Report Printing

As there is the likelihood that the reports can be of a considerable length it is strongly recommended that only the 80 Column printer with Z fold (tractor feed) paper be used. This is just as much for the memory storage of printer as it is for the reliable paper supply.

There is a HOLD.SET REPORT PRINT prompt under the main menu with the ability to print the pre-selected type of report. Pressing and holding the SET key for two seconds will initiate the printout. Any of the Log Reports will have the following format:

Custom Header Lines

Title of Report *<internally set, indicates report type>*

Current Date & Time
Instrument Serial No. & Tag

---------- *<separation line>*
Delivery No.
Date & Time & Status
Variable *unit* *value*
Variable *unit* *value*
etc.

---------- *<separation line>*
Delivery No.
Date & Time & Status
Variable *unit* *value*
Variable *unit* *value*
etc.

---------- *<separation line>*
Delivery No.
Date & Time & Status
Variable *unit* *value*
Variable *unit* *value*

ETC

Custom Footer Lines
---------- <*separation line*>

Reports such as “Latest Logs” will print in the historical order, and for those logs that have no data (e.g. unit was powered off at the time) the print will show “Data not available”. i.e.

---------- <*separation line*>
Del No. Data Not Available

---------- <*separation line*>
Delivery No.
Date & Time & Status
Variable unit value
Variable unit value
etc.

If the unit is programmed for 0 logs for the latest log reports then the report will only consist of the header and ID information and a “Data Not Available” message.

Custom Header Lines

Title of Report

Current Date & Time
Instrument Serial No. & Tag

Data Not Available

Custom Footer Lines
---------- <*separation line*>

Printer Data Control

Some printers have limited data buffers and are therefore unable to collect all the print data being transmitted. The 500 Series has the capability of software handshaking. The Xon/Xoff characters can be used by any of the printer types to control the flow of data to ensure that data is not lost.

Some printers will also transmit an Xoff character in response to other events such as printer being off-line, print head not engaged or power being removed. The specific behaviour of the printer being used should be noted.

Error Messages

There are two printer error messages that can be displayed.

PAPER OUT

This message is related to the Printer Type PRN-03 TM295 Slip printer. It is standard procedure with this printer to check for paper status before printing. If a print is attempted but there is no paper the PAPER OUT message will be scrolled. The instrument will continue to poll the printer for paper and if paper is detected before a communications timeout expires the print will commence.

COMMS TIMEOUT

This message is relevant for all printer types and will be activated for the following conditions.

1. If the flow of data is stopped due to software or hardware handshaking and is not allowed to resume before the communications timeout.

2. If Printer Type is PRN-03 Slip printer and a paper status is requested but no response is received within the timeout period.

3. Paper Out has been detected for Printer Type PRN-03 but no paper is inserted within the timeout period.

When a communications timeout error has been activated the message COMMS TIMEOUT will be scrolled once, the request to print will be cleared and the instrument will return to its normal mode.

Appendix A
Glossary

500-PM Software The 500 Series Program Manager (500-PM software) is a Windows based program that is freely available from the download section of the Contrec website. The program is a comprehensive configuration tool and resource centre that can be used to tailored an instrument to suit specific application needs including program settings, units of measurement, custom tags/text, access levels and more. Custom versions can be saved and configuration reports generated as a PDF.

ASCII American Standard Code for Information Interchange. For the ASCII protocol, the instrument receives and transmits messages in ASCII, with all command strings to the instrument terminated by a carriage return. Replies from the instrument are terminated with a line-feed and a carriage-return.

Filtering The process of suppressing oscillations or random signals in the input signal.

K-factor The K-factor is a constant value associated with frequency type flowmeters. It is a scaling factor used in calculations to determine volumetric flow rate.

Linear Correction A scaling of the input signal to represent the actual flow parameter.

Modbus RTU The Modbus protocol is a message structure for communications between controllers and devices regardless of the type of network. In RTU (remote terminal unit) mode, each 8-bit byte in a message contains two 4-bit hexadecimal characters. This mode has greater character density than ASCII and allows better data throughput than ASCII for the same baud rate.

Normalised Input A normalised input ranges from 0 to 1.000. For 4-20 mA input, the signal is set to 0 at 4 mA and the signal is set to 1.000 at 20 mA.

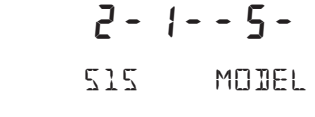
NPS Namur Proximity Switch.

Passive Output Signal Requires an external power supply.

Watchdog Timer (WTD) The WDT is used to monitor the activity of the micro processor and will force a re-boot if the micro processor stops, while power is applied, due to any internal or external influences.

Appendix B
Model Numbers

Product Codes

Model	Supplementary Code						Description
515 .						**- BC03**	
Enclosure	1						Panel mount enclosure
	2						Field mount enclosure (NEMA 4X / IP66)
	3/5						Explosion proof Ex d (IECEx/ATEX), metric glands (5 specifies heater)
	4/6						Explosion proof Ex d (CSA), NPT glands (6 specifies heater)
Output Options		0					4 logic inputs, 1 isolated output, 2 relays (only relay type 1 is available), RS232 (DB9) communication port
		1					4 logic inputs, 2 isolated outputs, 4 relays, real-time clock data logging, RS232 (DB9) and RS485 communication ports
		2					4 logic inputs, 2 isolated outputs, 4 relays, real-time clock data logging, RS232 (DB9) and Ethernet communication ports
Relay Type			1				Electromechanical relays only
			2				2 electromechanical and 2 solid state relays
			3				Solid state relays only
Power Supply				U			Inputs for 12-28VDC and 100-240 VAC, 50-60Hz *(Previous Models: A = 110/120 VAC, E = 220/240 VAC)*
				D			Input for 12-28VDC power only
Display Panel Options					S		Standard option (now with backlight & LCD backup) *(original Full option: F, with Infra-Red comms, no longer available)*
PCB Protection						C	**Conformal coating** - required for maximum environmental operating range. Recommended to avoid damage from moisture and corrosion.
						N	**None** - suitable for IEC standard 654-1 Climatic Conditions up to Class B2 (Heated and/or cooled enclosed locations)
Application Pack Number						**BC03**	Defines the application software to be loaded into the instrument
For example: Model No. 515.111USC Displayed on the 500 Series as: Note: The first character represents the CPU installed (factory use only). The remaining 6 characters only represent hardware that affects the operation.							

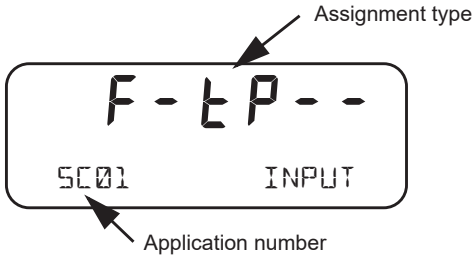
Note: Example full product part number is 515.111USC-BC03 (this is the number used for placing orders).

Custom Version Codes

	Code		Description
Origin Code **Identifies Distributor**	00		Factory Default Application
	01		Contrec Systems Pty. Ltd. Melbourne Australia
	02		Contrec Limited. West Yorkshire UK
	03		
	04		Contrec-USA, LLC. Pelham AL 35124 USA
	05		Flowquip Ltd. Halifax UK
	06		
	etc.		
User Language	0		English (Default)
	1		German
	2		Dutch
	3		French
	4		Spanish
	5		
	etc.		
Distributor's Code		000 … 999	Distributor's own choice. Possibly a code that identifies the customer and the application.
For example: 02 3 157 Displayed on the 500 Series as:			023157 CUSTOM VERS

Application Information Code

The Application Information code is an aid for users and service personnel to determine the type of inputs that are used in a particular application. The Application Information code is displayed on the instrument as shown below.



The Application Information code is returned as part of a General Instrument request (as described in **Instrument Information Request** on page 66).

The Application number identifies the application as in the following examples:

- SC01 - steam flow computer for frequency flow meter
- GN02 - natural gas flow computer for analog flow meter

The Input Assignment type indicates the physical input that is assigned to each input on the instrument. The code is made up from six characters as follows:

FINP1	FINP2	AINP1	AINP2	AINP3	AINP4
X	X	X	X	X	X

The codes are as follows:

- - - not used in this application
- A - indicates a generic analog input such as for density or level
- d - indicates a density input
- F - indicates a generic flow input such as for volume or mass, (frequency or analog)
- H - indicates a high flow input for stacked inputs
- L - indicates a low flow input for stacked inputs
- P - indicates a pressure input
- q - indicates a quadrature input
- t - indicates a temperature input.

For example, F-tP-- is an instrument with FINP1 (frequency input 1) assigned to a flow input, AINP1 assigned to a temperature input and AINP2 assigned as a pressure input. The other inputs are not used.

Appendix C
Units of Measurement

Available Units of Measurement

The following is a list of the available units of measurement used across the range of 500 Series applications.

Units Type	Available units of measurement
Volume	m^3, Km^3, Ltr, mL,Gal, KGal, MGal, ft^3, kft^3, Mft^3, bbl
Volume Flowrate	m^3/s, m^3/min, m^3/h, m^3/D, L/s, L/min, L/h, L/day, mL/s, mL/min, mL/hr, Gal/s, Gal/min, Gal/h, KGal/D, MGal/D, ft^3/s, ft^3/min, ft^3/h, Mft^3/D, bbl/s, bbl/min, bbl/h, bbl/D
Volume K-Factor	P/m^3, P/Ltr, P/mL, P/Gal, P/ft^3, P/bbl
Mass	kg, g, Ton, lb, Klb
Mass Flowrate	kg/s, kg/min, kg/h, g/s, g/min, g/h, Ton/min, Ton/h, Ton/D, lb/s, lb/min, lb/h, Klb/min, Klb/h, Klb/D
Mass K-Factor	P/kg, P/g, P/Ton, P/lb, P/Klb
Energy	kJ, MJ, GJ, kWh, MWh, kBTU, Ton.h, therm, cal, kcal, Mcal
Power	kJ/h, MJ/h, GJ/h, kW, MW, kBT/M, kBT/h, Ton, therm/min, therm/h, kcal/h, Mcal/h
Energy K-Factor	P/kJ, P/kWh, P/kBTU, P/Ton.h, P/therm, P/kcal
Temperature	Deg K, Deg C, Deg F, Deg R
Pressure	Pa, kg/m^2, kg/cm^2, kPa, MPa, mbar, bar, psi, Atm, inH_2O, mmH_2O
Density	kg/m^3, kg/Ltr, lb/ft^3, SG60F
Specific Volume	m^3/kg, L/kg, ft^3/lb
Specific Enthalpy	kJ/kg, BT/lb, cal/g, cal/kg, kcal/kg, Mcal/kg
Reynolds Number	E+0, E+3, E+6 (scaling for unitless variable)
Length (Level)	m, mm, cm, INCH, FOOT
Velocity	m/s, m/M, m/h, ft/s, ft/M, ft/h
Length K-Factor	P/m, P/cm, P/INCH, P/FOOT
Area	m^2, ft^2
Ratio	%
General Input	Pressure, Temperature, Density, Length (Level), Factor

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W